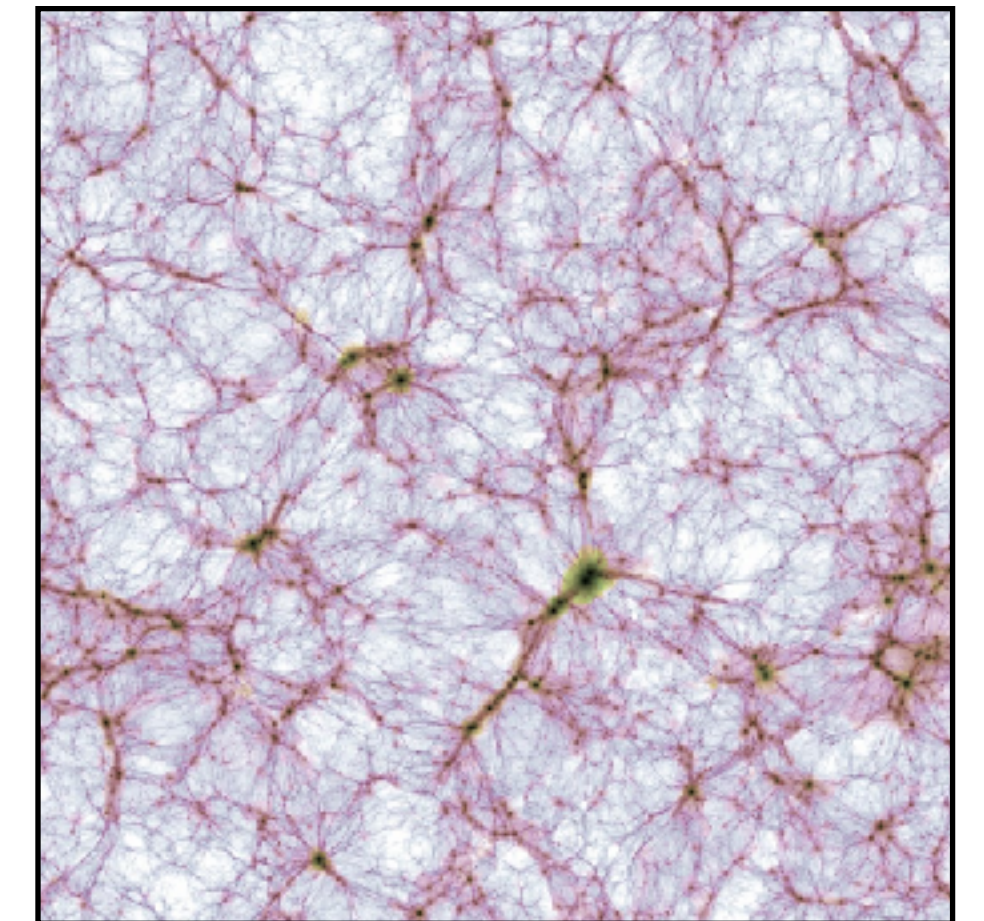
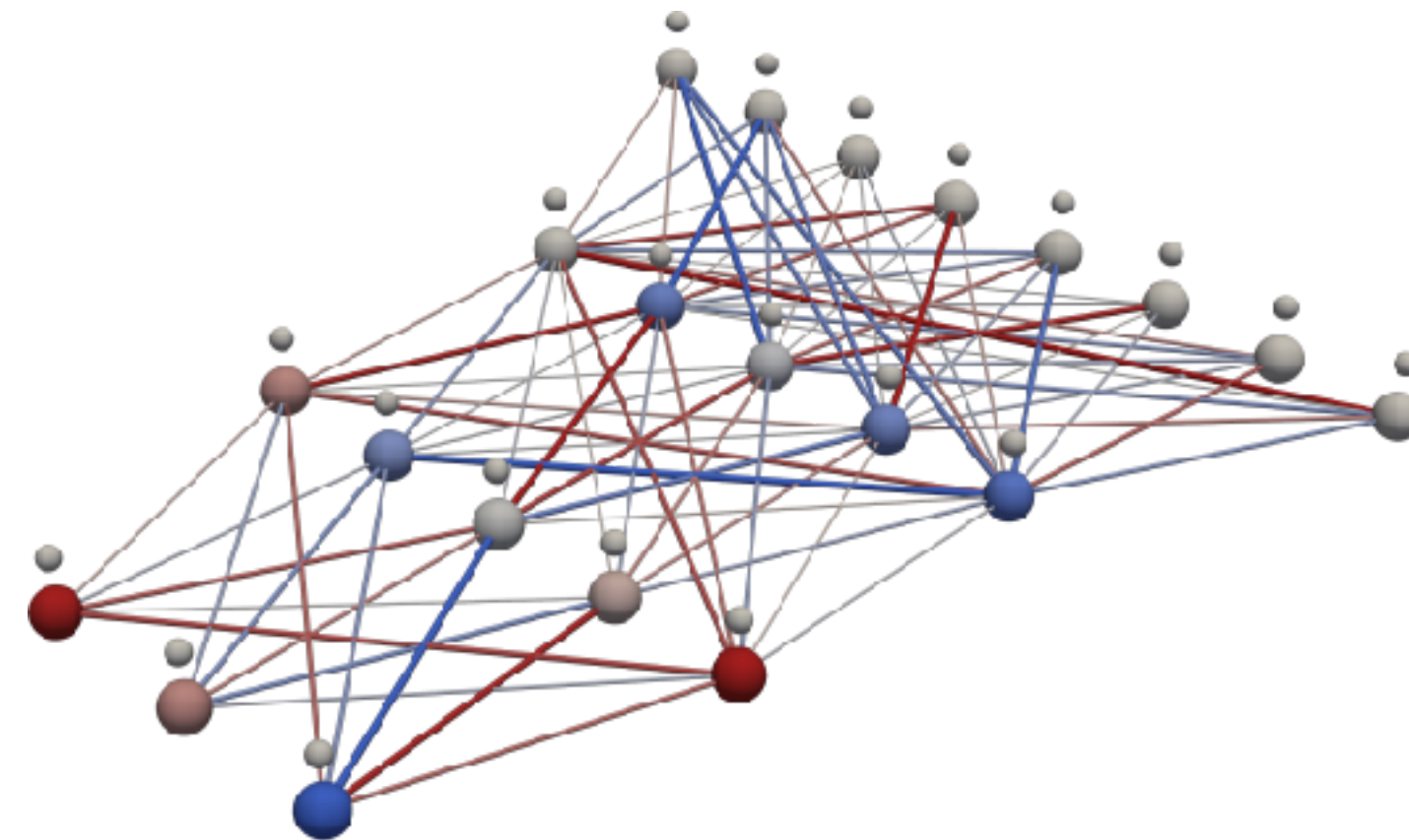
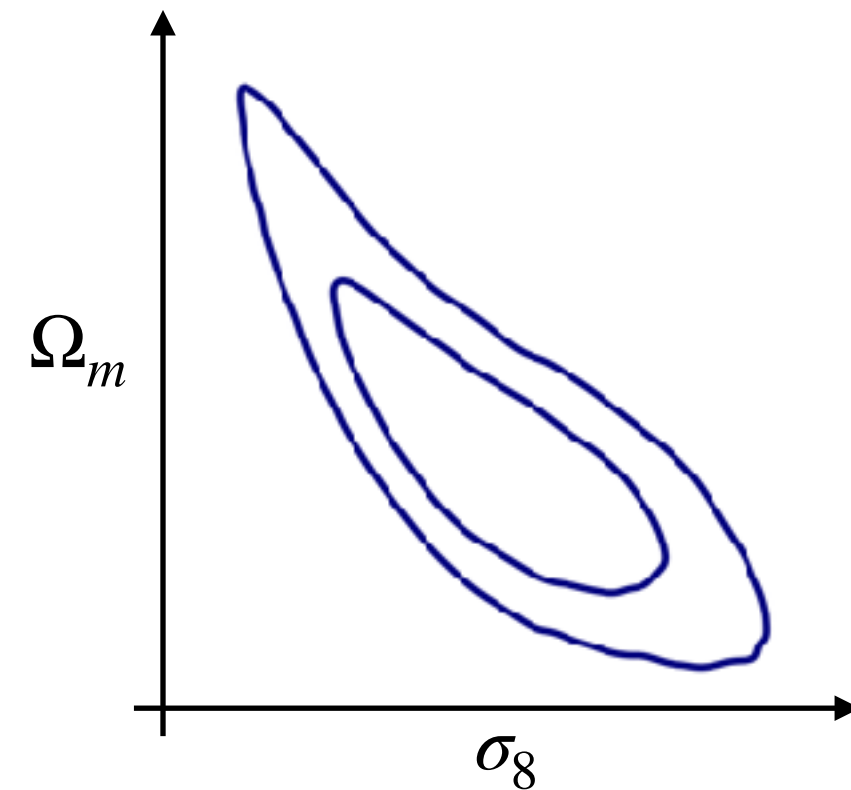



SBI has its own Dodelson-Schneider effect (but it knows!)



Jed Homer

Workshop on "Cosmological Inference" | MPA | 07/07/26

 2412.02311

 LMU PHYSIK

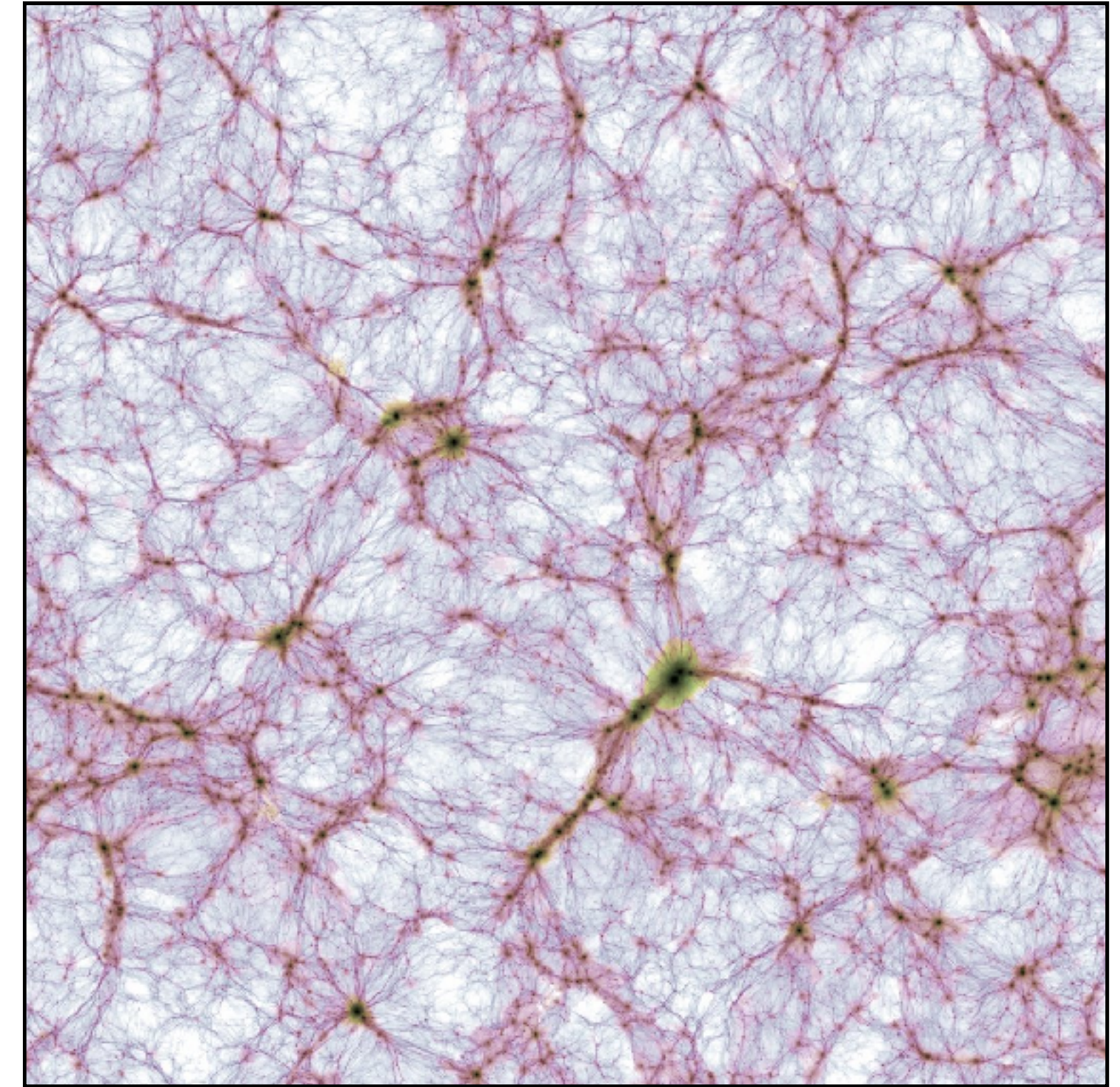
 ORIGINS
Excellence Cluster

 MCMML
Munich Center for Machine Learning

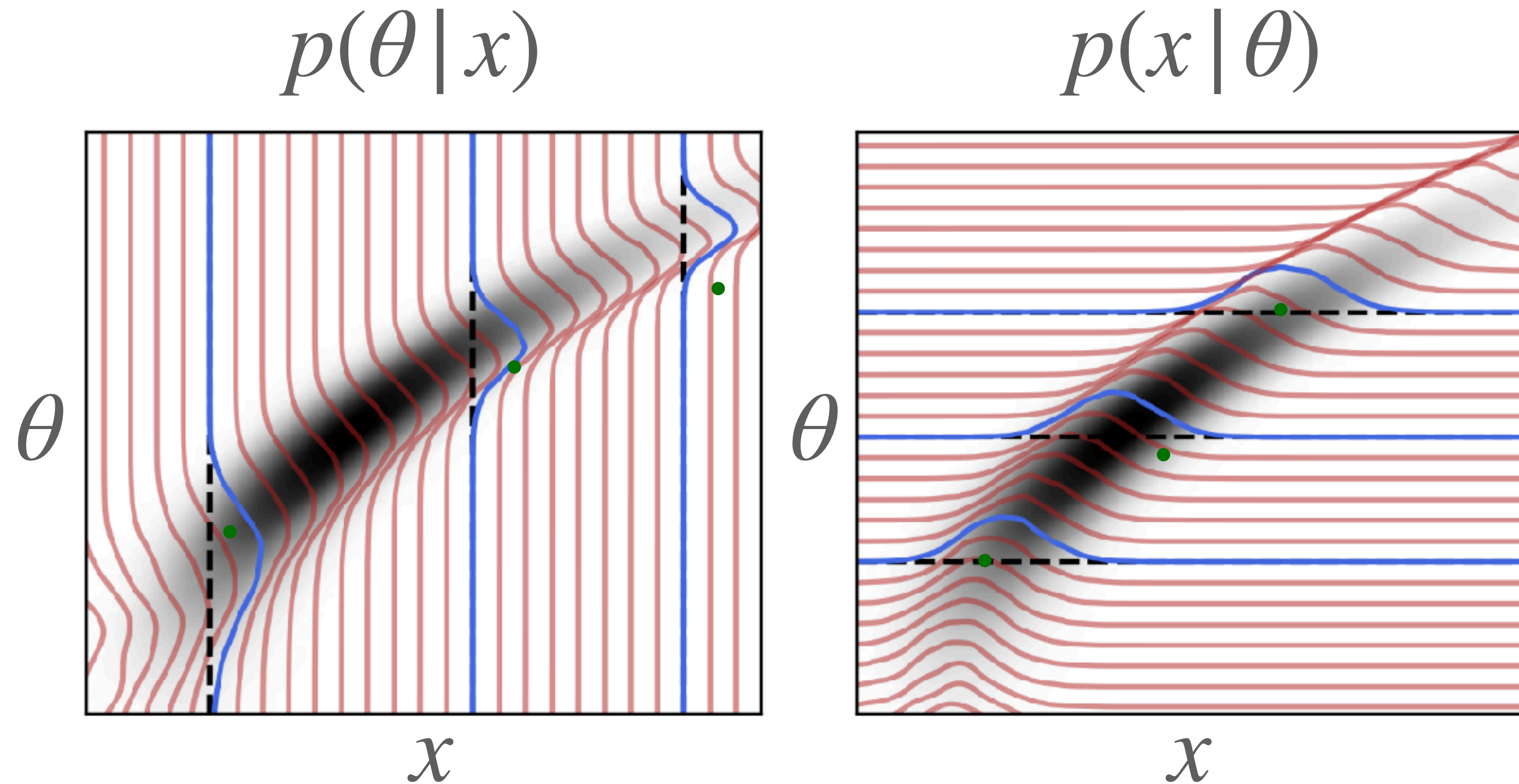
Why simulation-based inference (SBI)?

$$p(\theta | \hat{x}) \propto p(\hat{x} | x[\theta], \theta) p(\theta)$$

- Likelihood $p(\hat{x} | \theta)$ may be non-Gaussian
- Expectation $x[\theta]$ is a complex non-linear function of θ
- Covariance Σ may depend on θ
- n_x is increasing with new surveys, inversion of $\hat{\Sigma}$



Simulation-based inference (SBI)

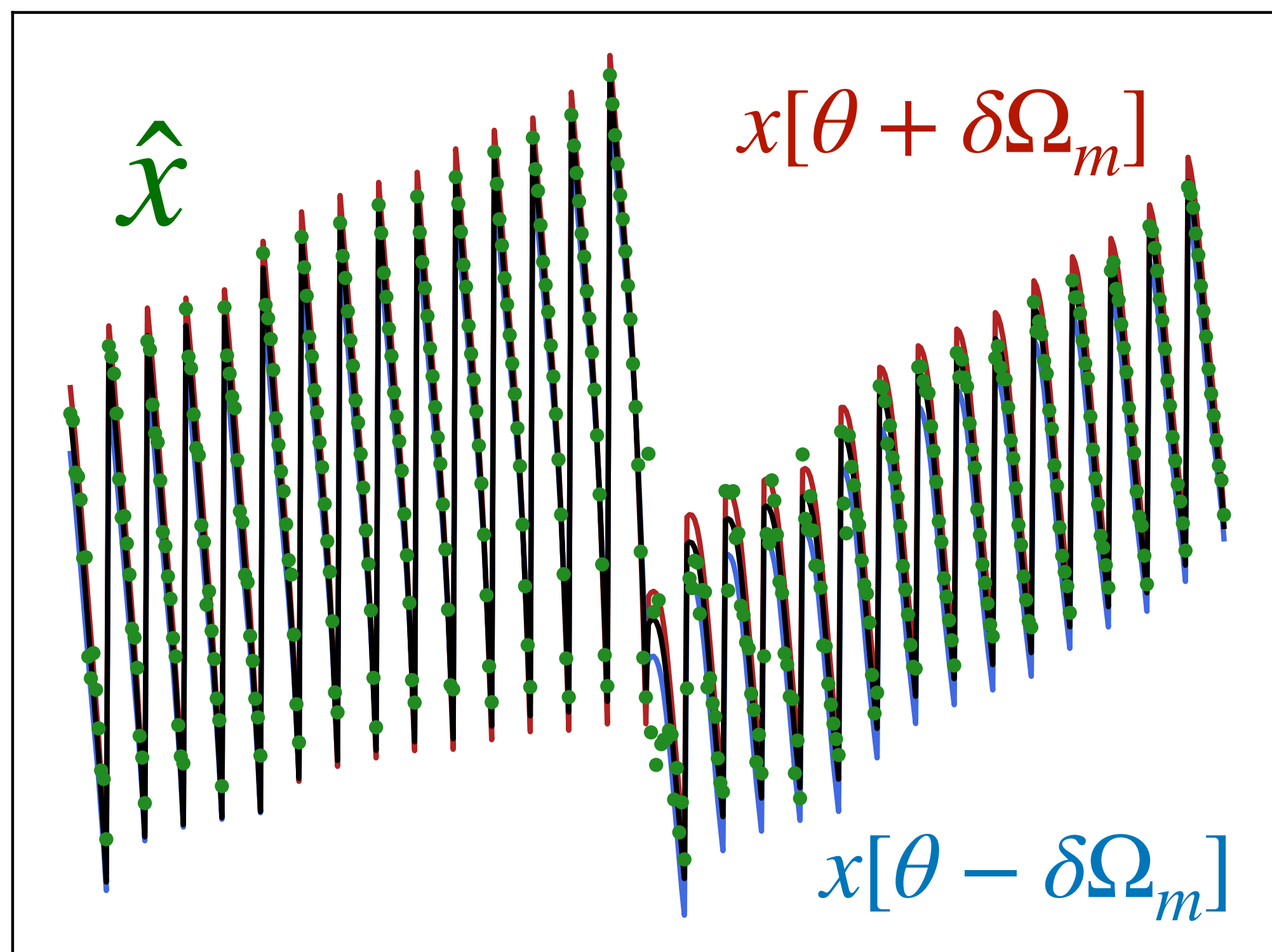


- **Analytic methods:** model PDF across space (x, θ)
- **SBI:** fit the expectation $x[\theta]$, covariance Σ and PDF $p(\hat{x} | \theta)$ from simulations (x, θ)

$$\hat{x} \sim \mathcal{G}[\hat{x} | x[\theta], \Sigma]$$

$x[\theta]$

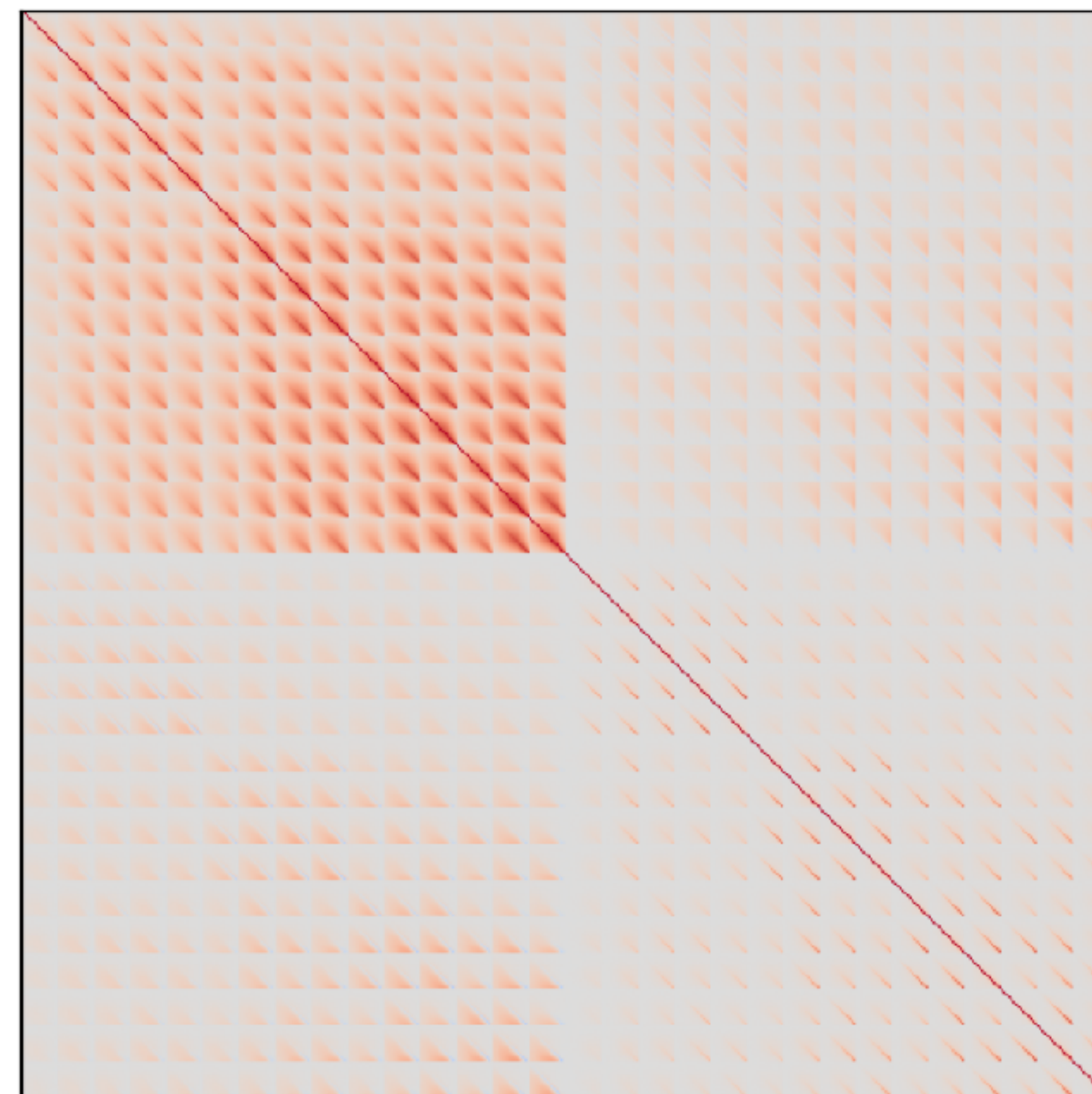
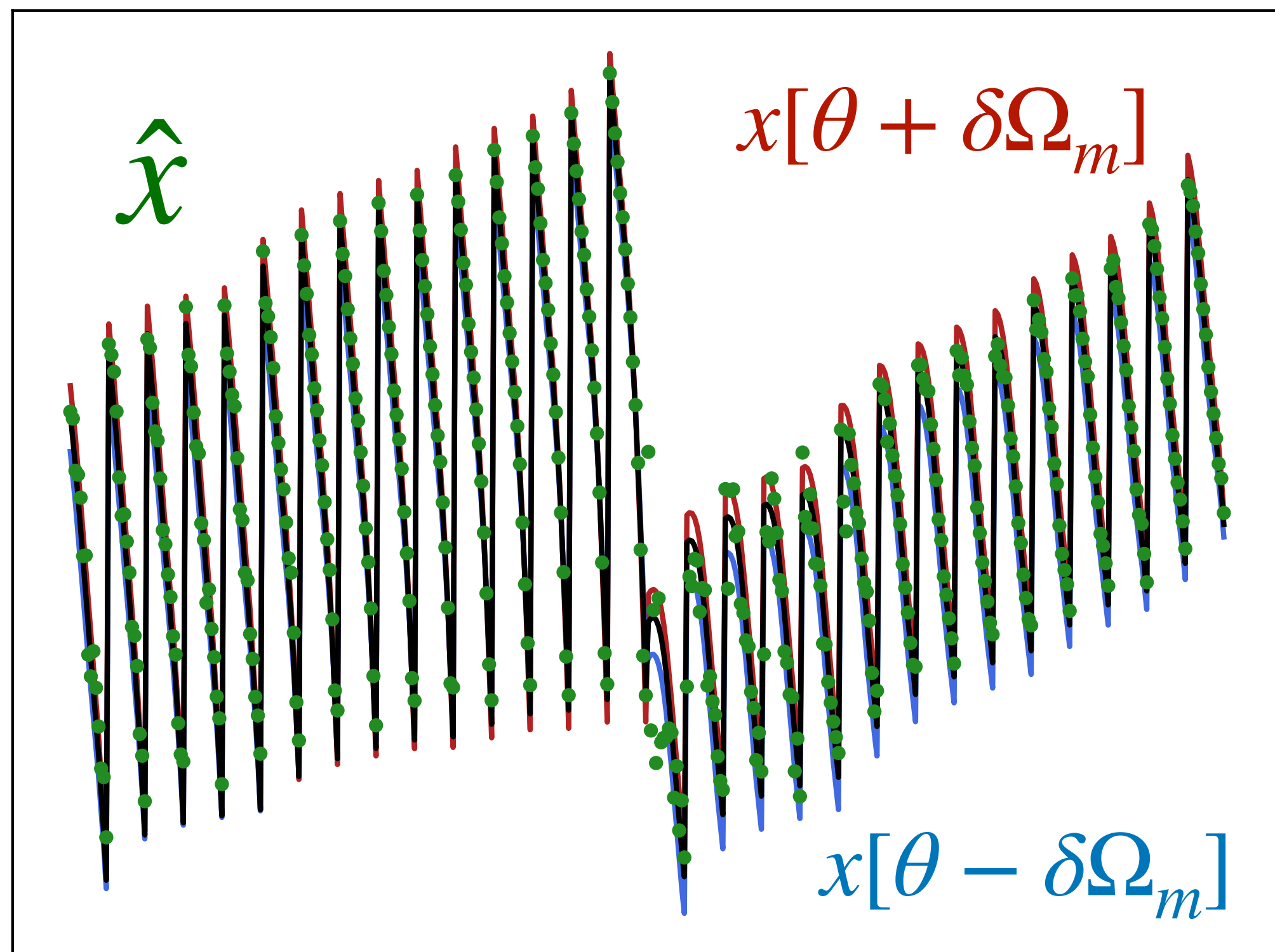
Σ



$$\hat{x} \sim \mathcal{G}[\hat{x} | x[\theta], \Sigma]$$

$x[\theta]$

Σ



Best-fit $\hat{\theta}$ with estimated covariance $\hat{\Sigma} \neq \Sigma$

- Estimating **best-fit** $\hat{\theta}$ from \hat{x} with an **estimated covariance** $\hat{\Sigma}$

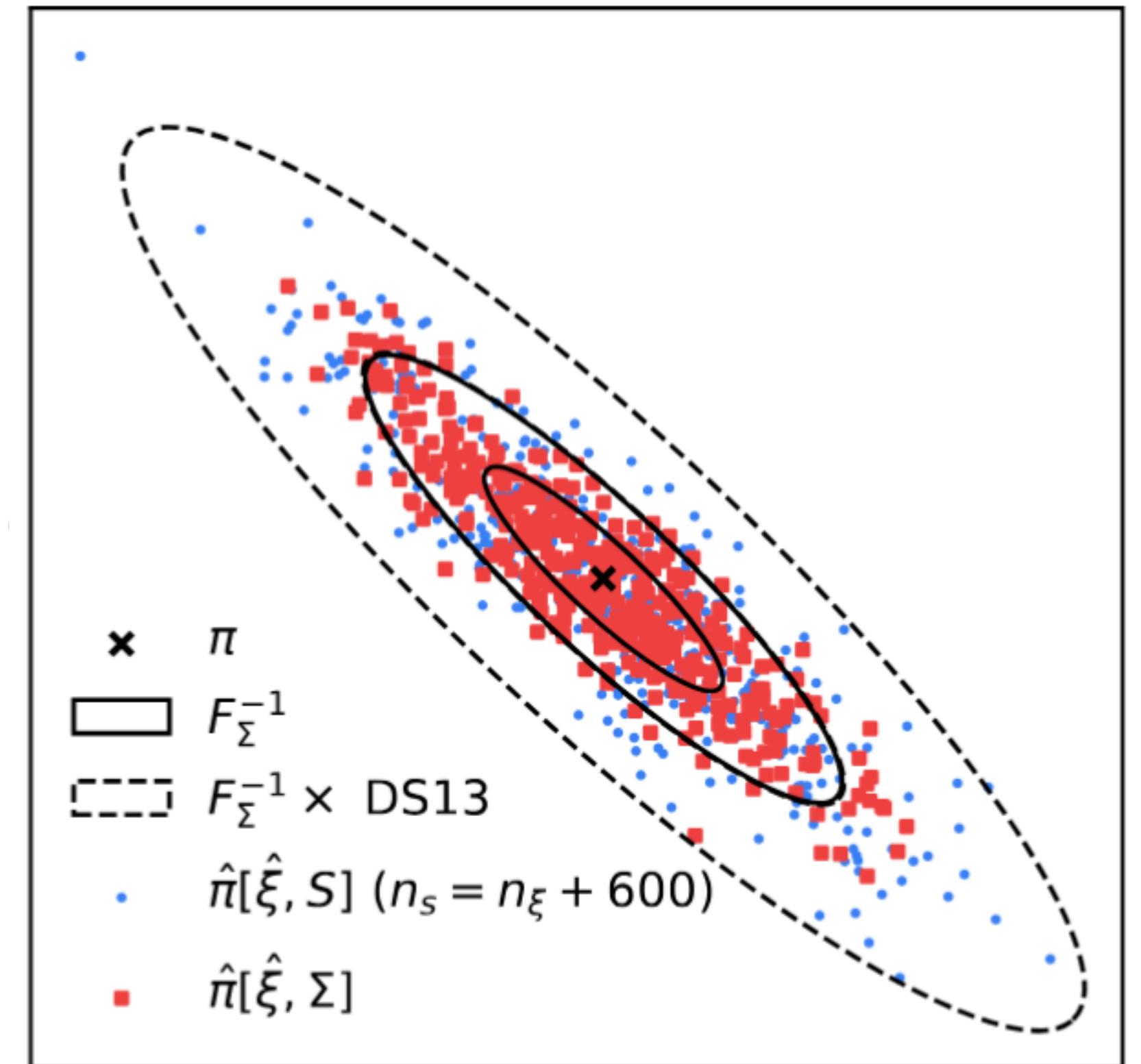
$$\hat{x} \sim \mathcal{G}[\hat{x} | x[\theta], \Sigma]$$



$$\hat{\theta} = \theta + M[\hat{\Sigma}^{-1}] (\hat{x} - x[\theta])$$

$\hat{\Sigma}^{-1}$ Σ^{-1}

Ω_m



σ_8

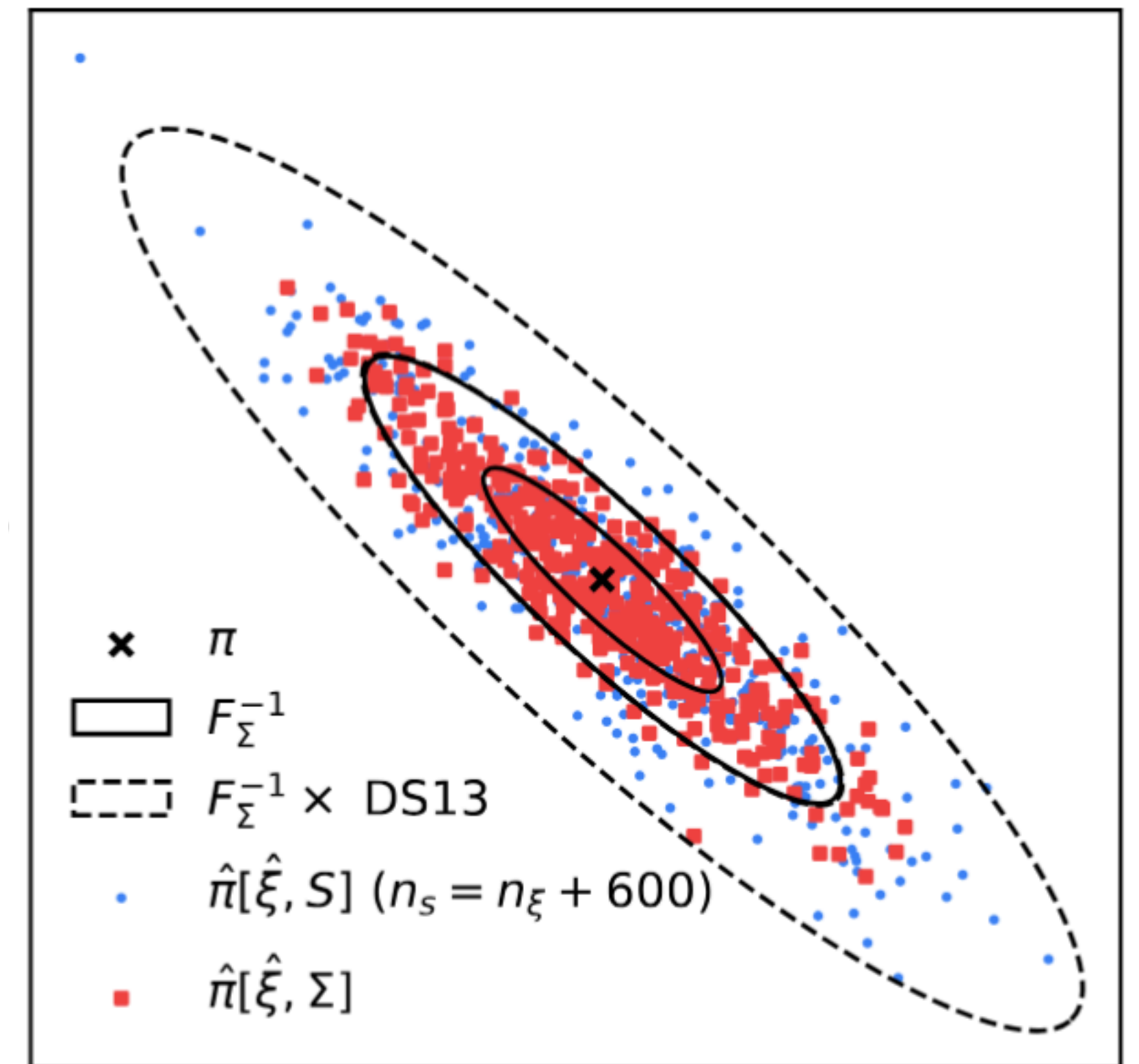
The Dodelson-Schneider Effect

- Estimate the covariance $\hat{\Sigma}$ with n_s simulations

$$\hat{\theta} = \theta + M[\hat{\Sigma}^{-1}] (\hat{x} - x[\theta])$$

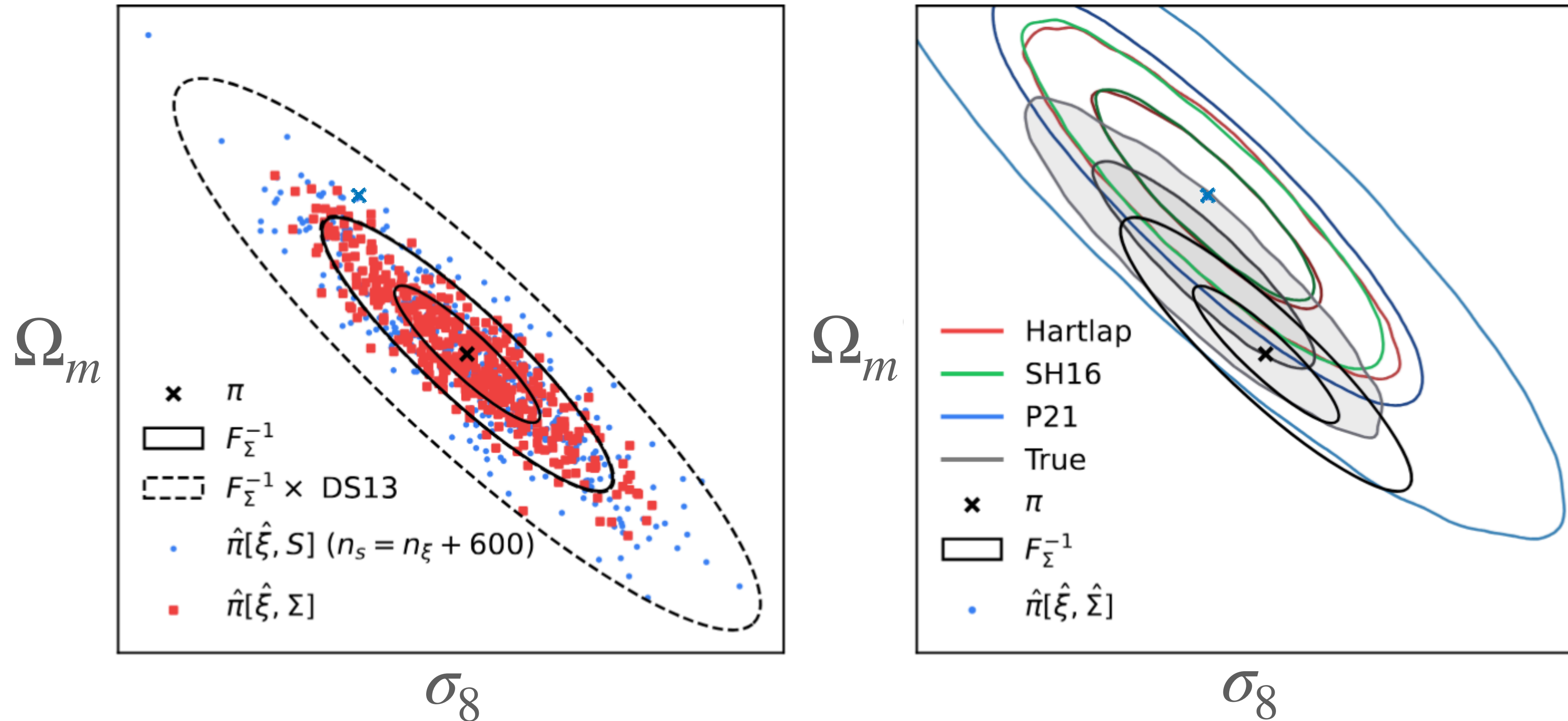
$$\hat{\Sigma}_{\theta} = \Sigma_{\theta} \left[1 + \frac{n_x - n_{\theta}}{n_s - n_x} \right]$$

Ω_m



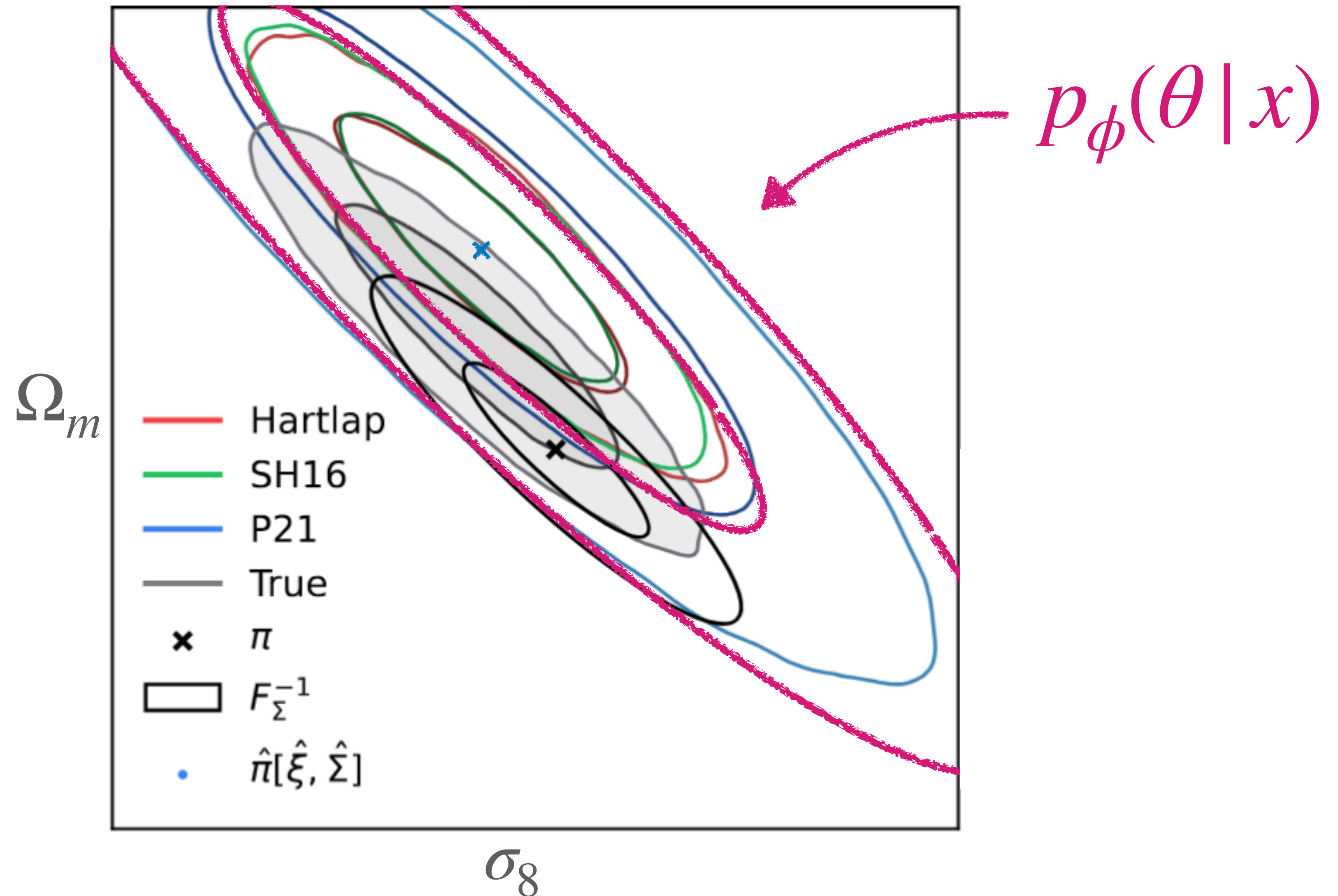
σ_8

Problem: estimating θ from \hat{x} when $\hat{\Sigma} \neq \Sigma$

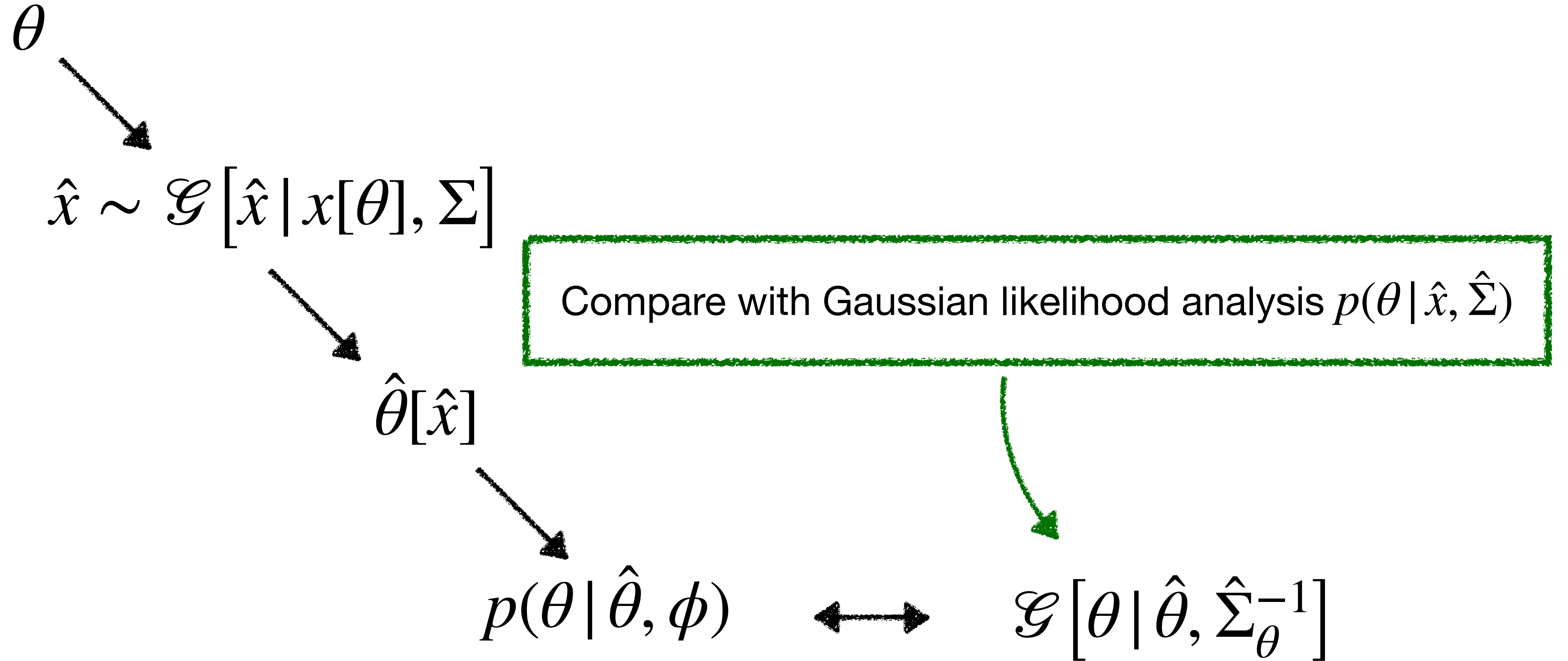


Noise in $\hat{\Sigma} \neq \Sigma$ adds scatter to best-fit $\hat{\pi}$. Not accounted for in Gaussian ansatz.

What contour does SBI draw?



Analytic testing of SBI



Analytic testing of SBI

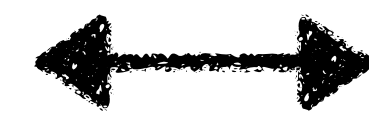
θ

$$\hat{x} \sim \mathcal{G}[\hat{x} | x[\theta], \Sigma]$$

$\hat{\theta}[\hat{x}]$

n_s

$$p(\theta | \hat{\theta}, \phi)$$



$$\mathcal{G}[\theta | \hat{\theta}, \hat{\Sigma}_{\theta}^{-1}]$$

$$\hat{\theta} = \text{NN}(\hat{x})$$

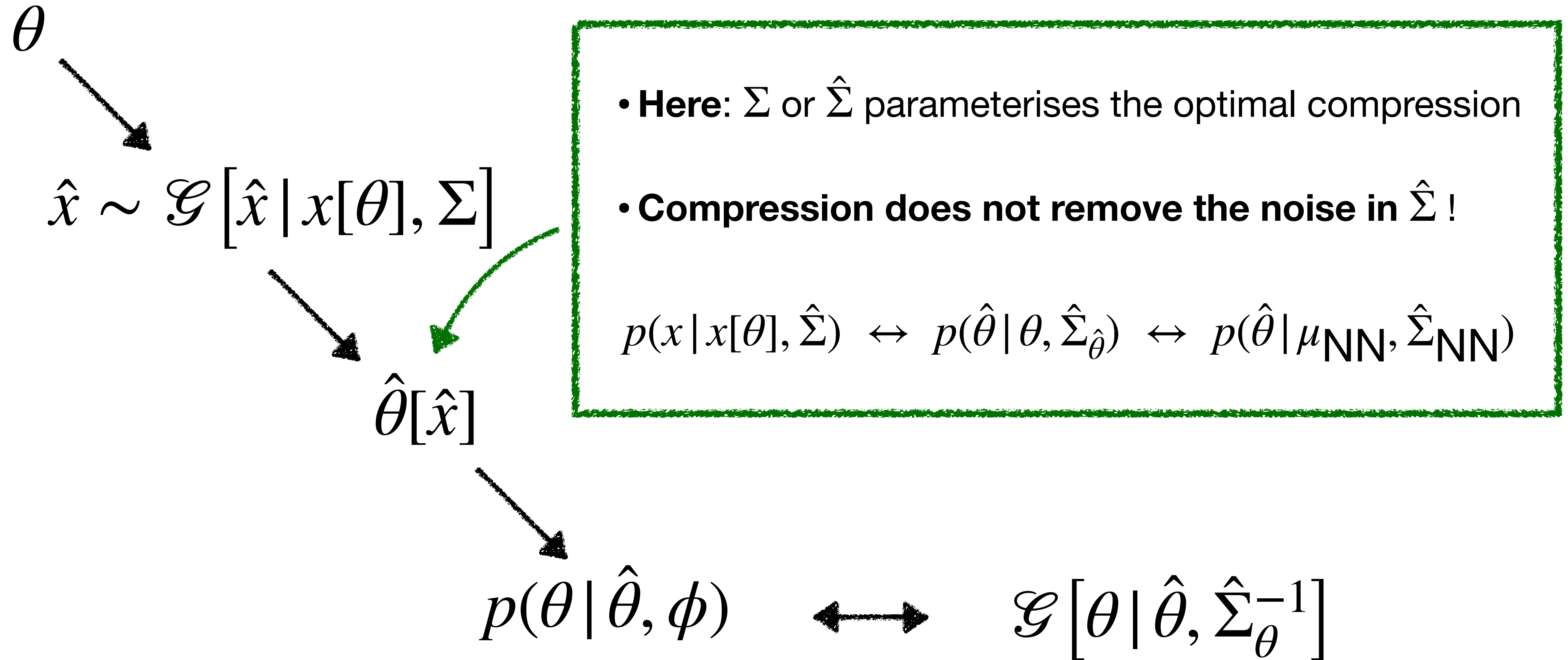
n_s

$$\hat{\theta} = M[\Sigma]\hat{x}$$

$$\hat{\theta} = M[\hat{\Sigma}]\hat{x}$$

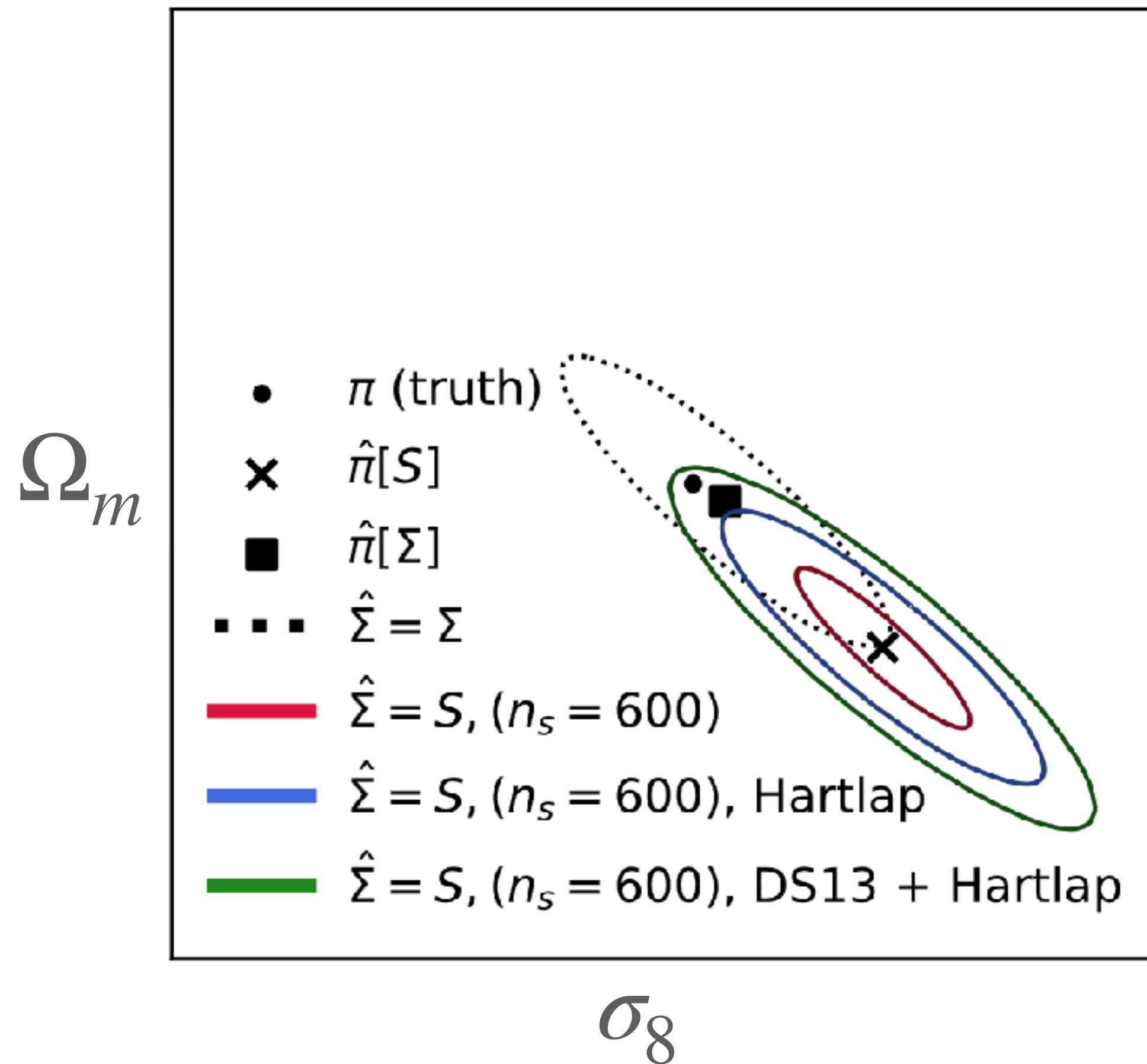
n_s

Analytic testing of SBI



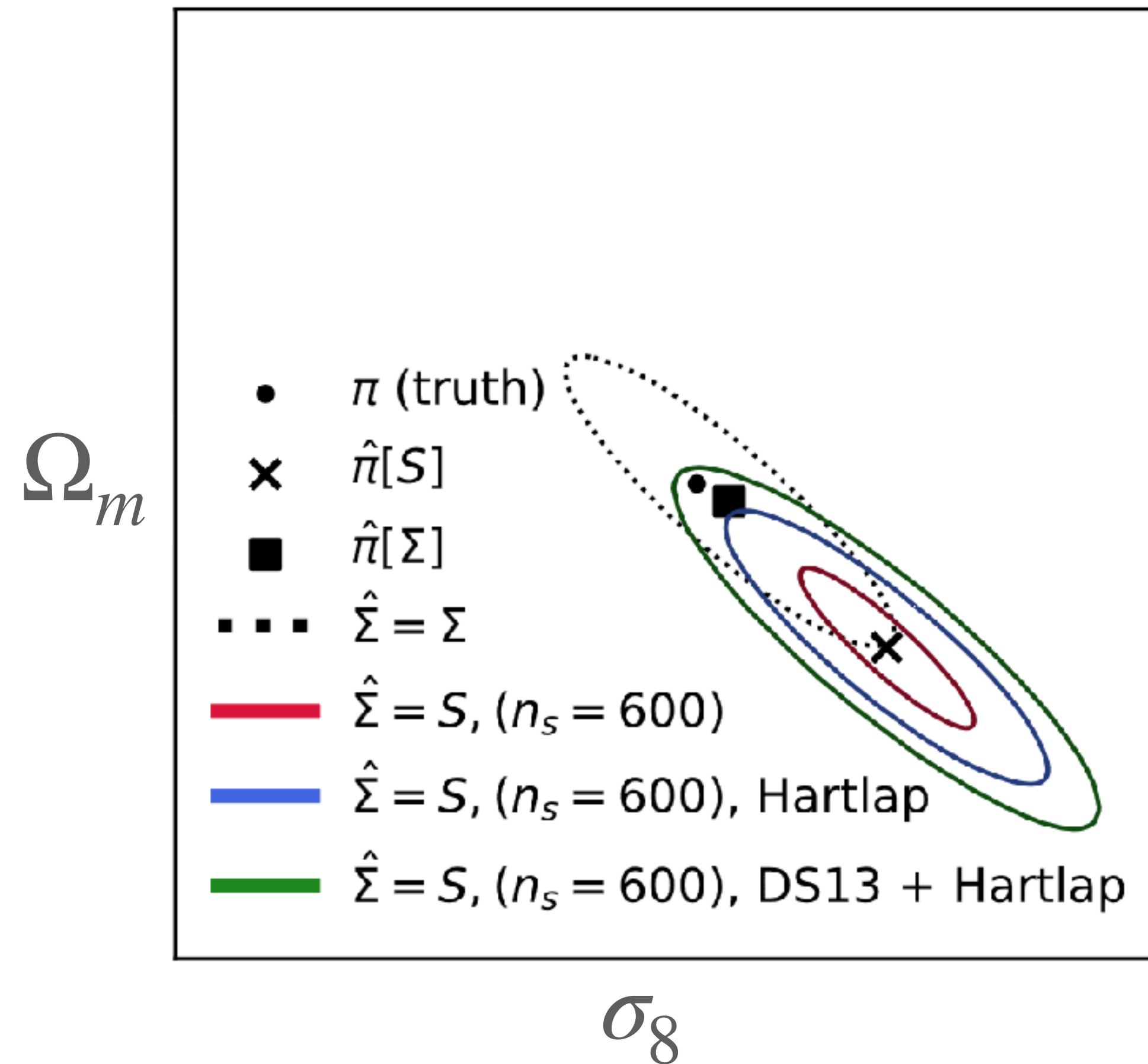
The good and bad news about SBI

Gaussian likelihood analysis

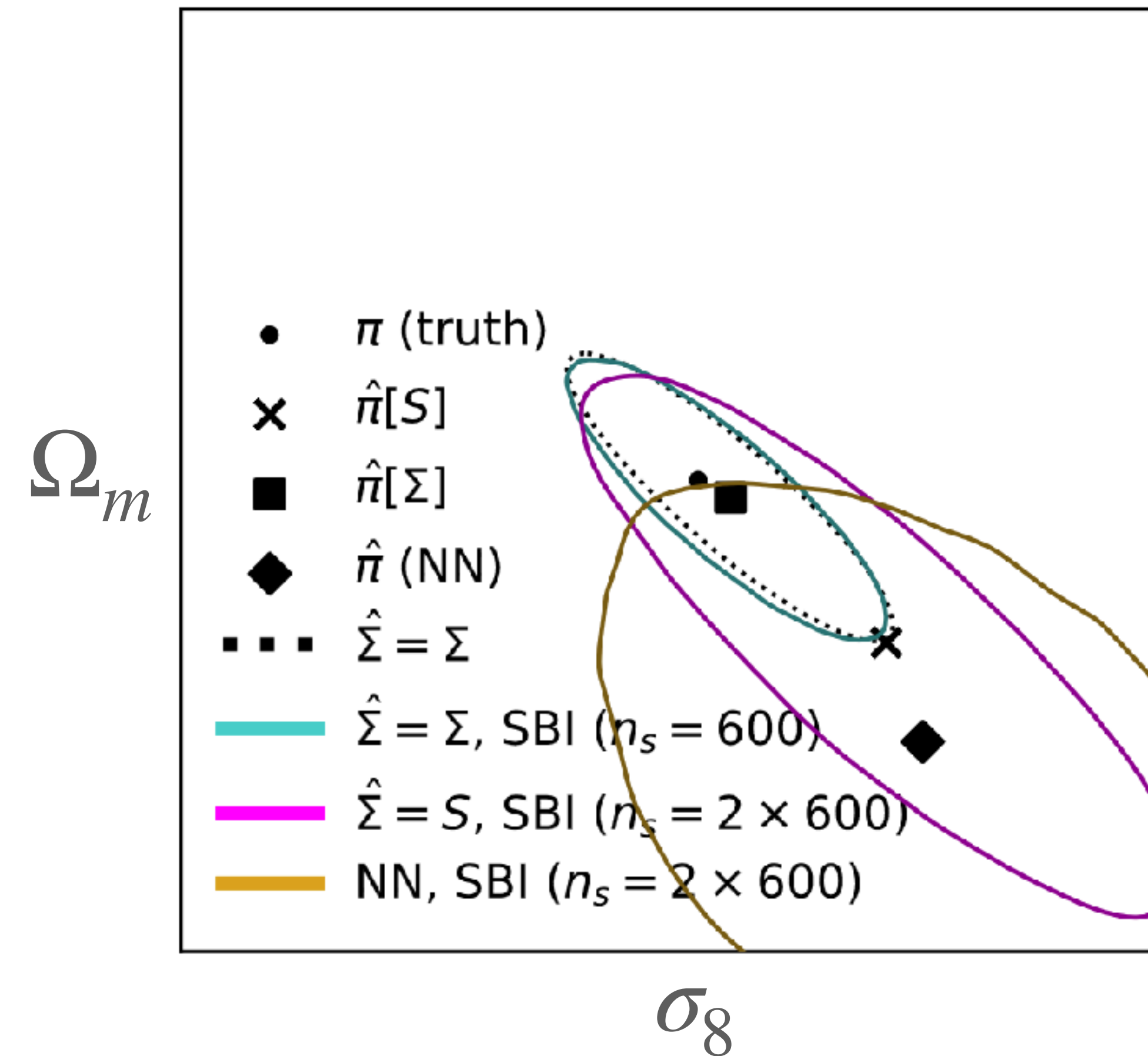


The good and bad news about SBI

Gaussian likelihood analysis

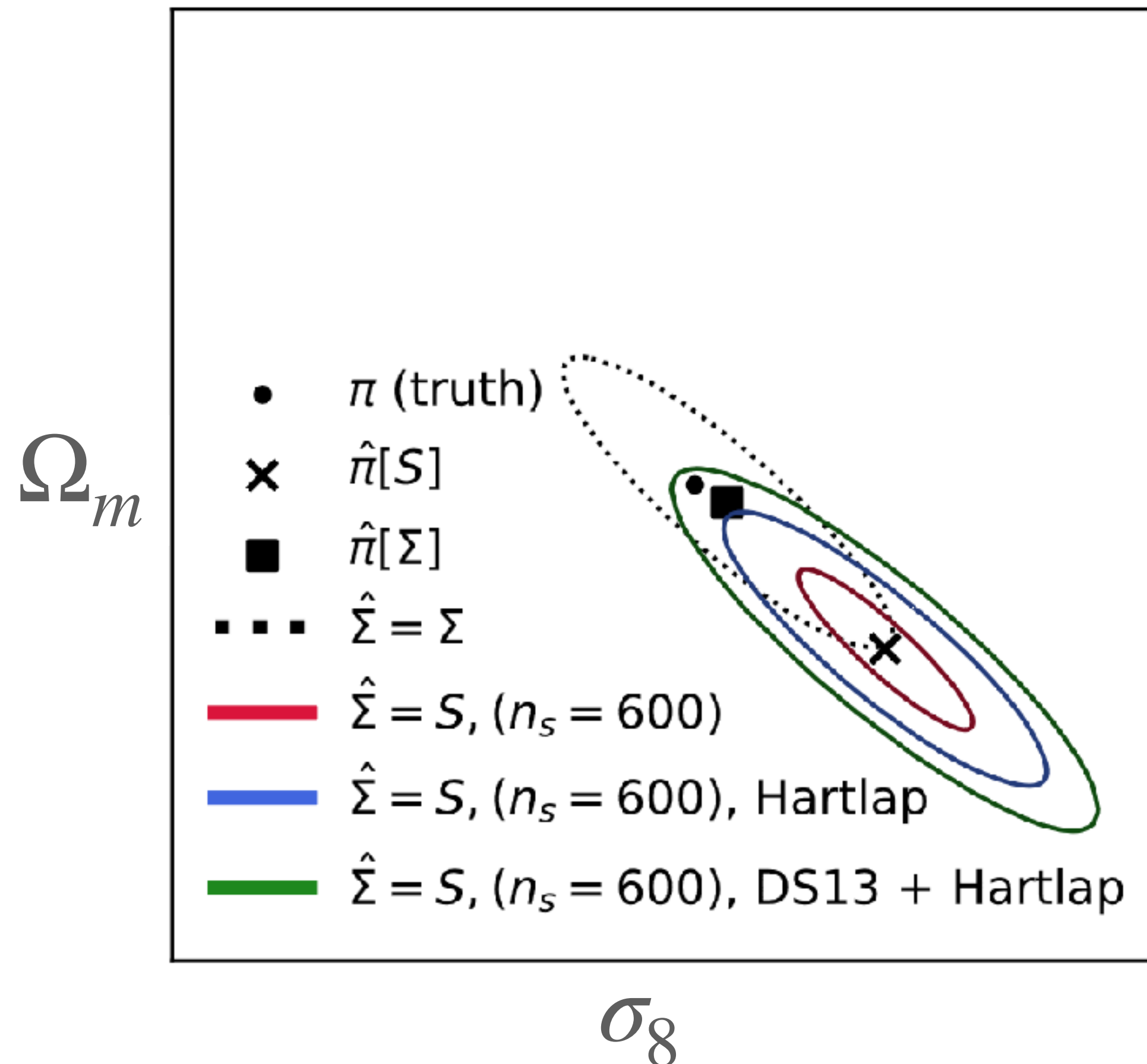


Simulation-based inference

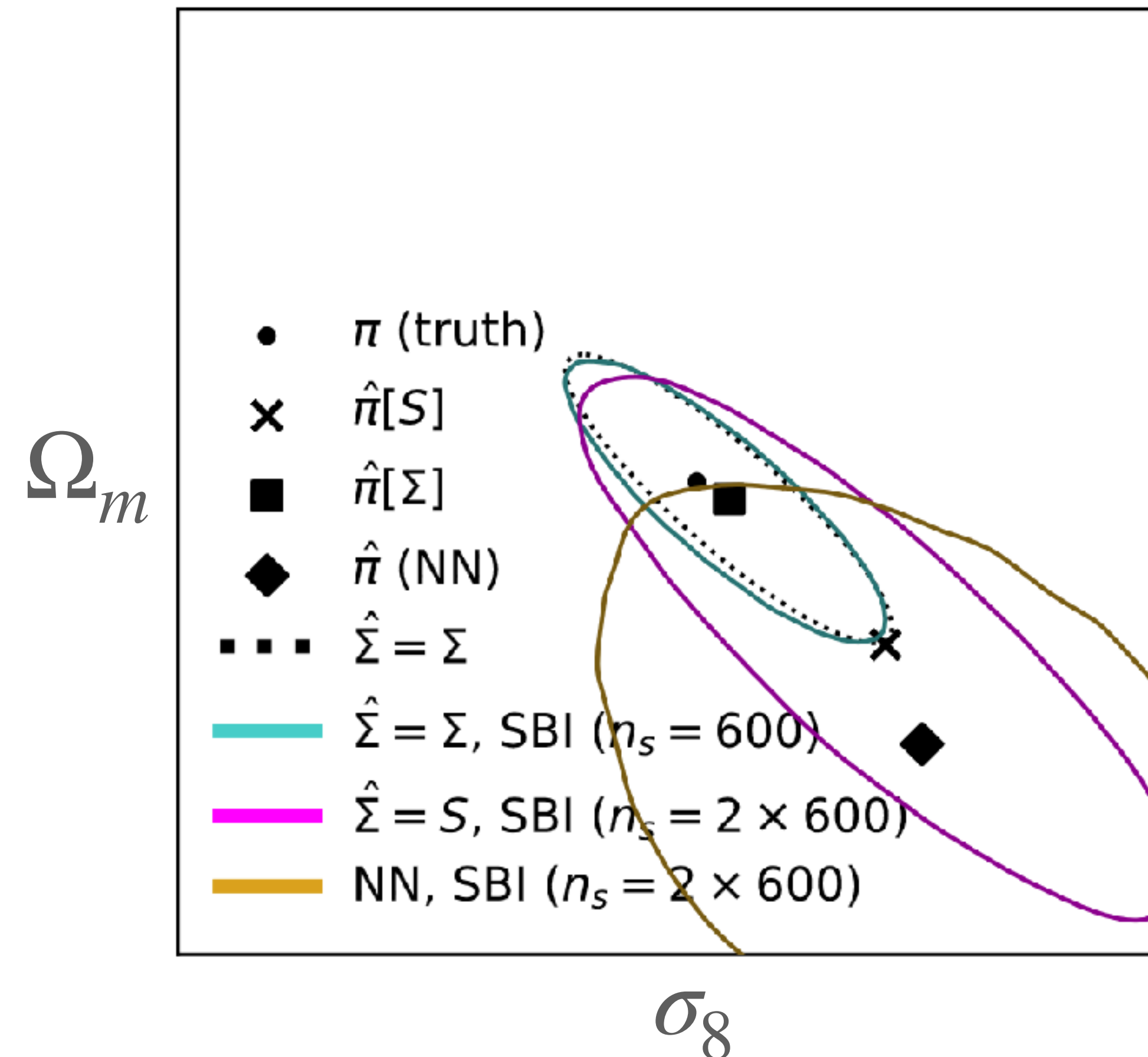


The good and bad news about SBI

Gaussian likelihood analysis

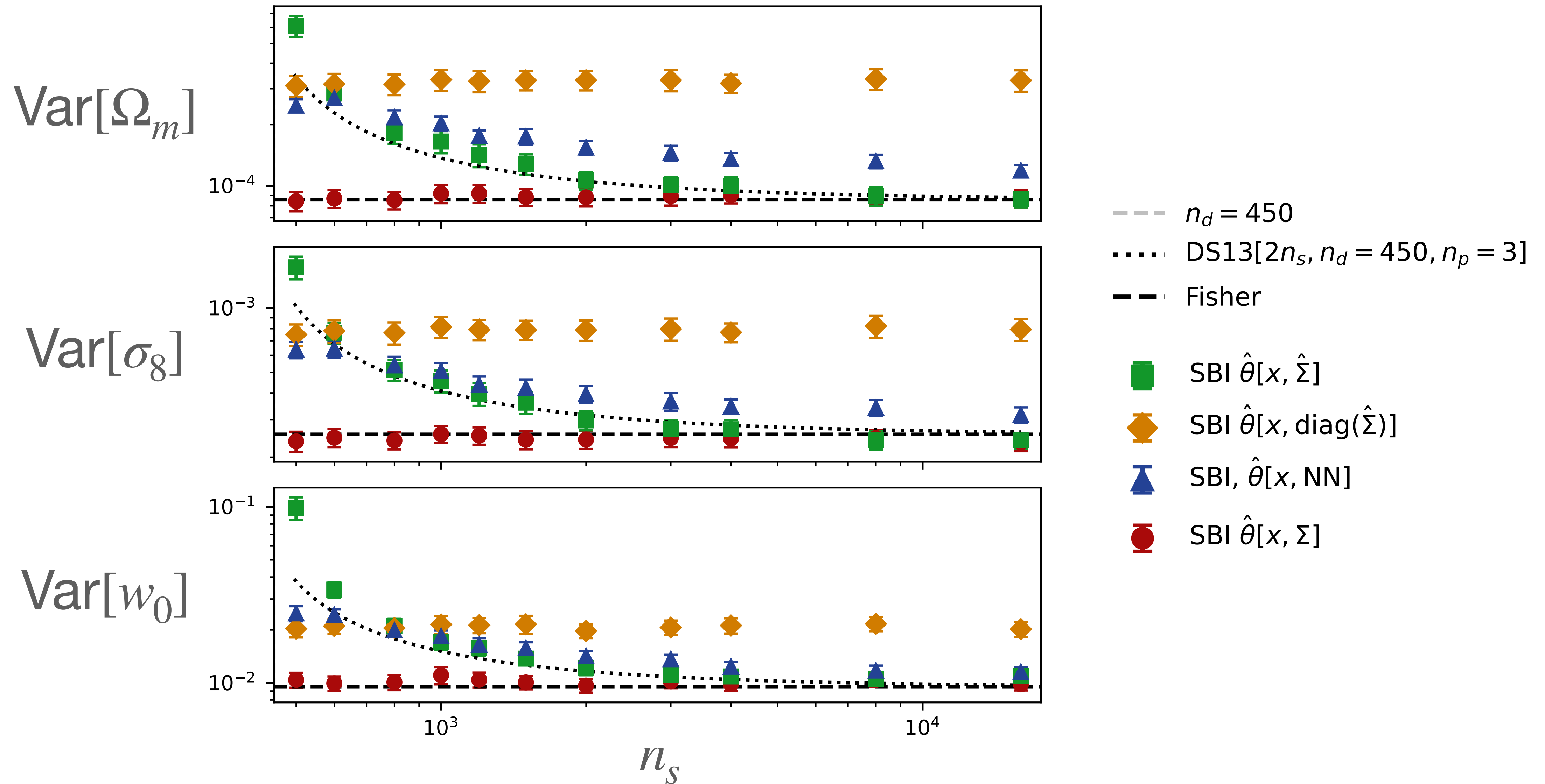


Simulation-based inference

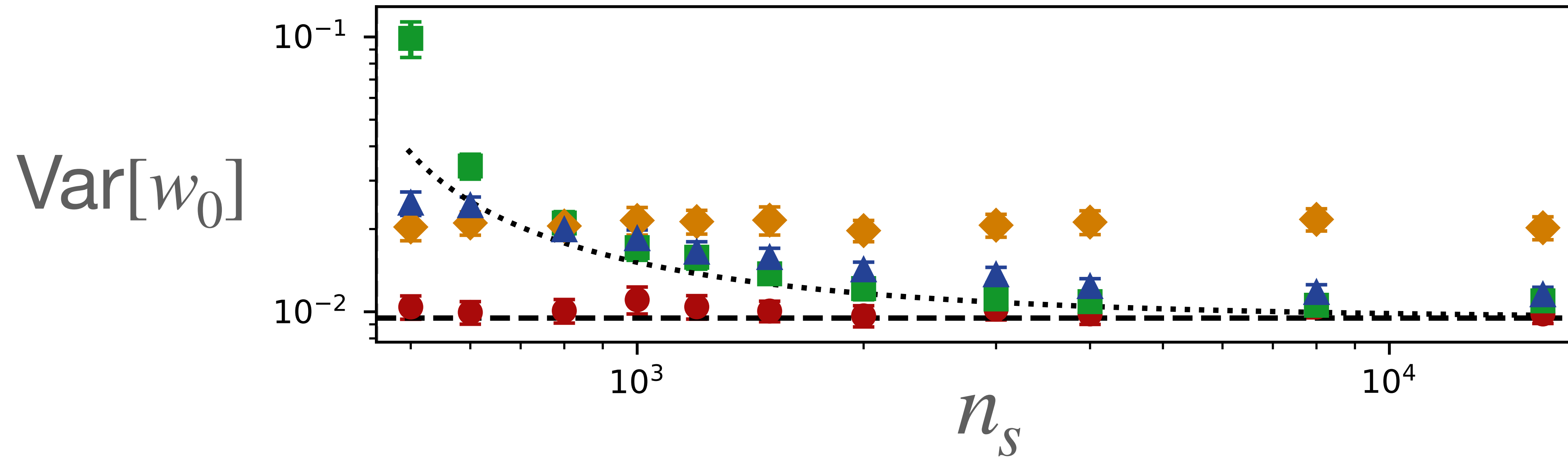


SBI is aware of the Dodelson-Schneider effect but it is inefficient in its response!

Posterior widths: SBI vs. Gaussian likelihood analysis



Posterior widths: SBI vs. Gaussian likelihood analysis



--- $n_d = 450$

..... DS13[$2n_s, n_d = 450, n_p = 3$]

--- Fisher

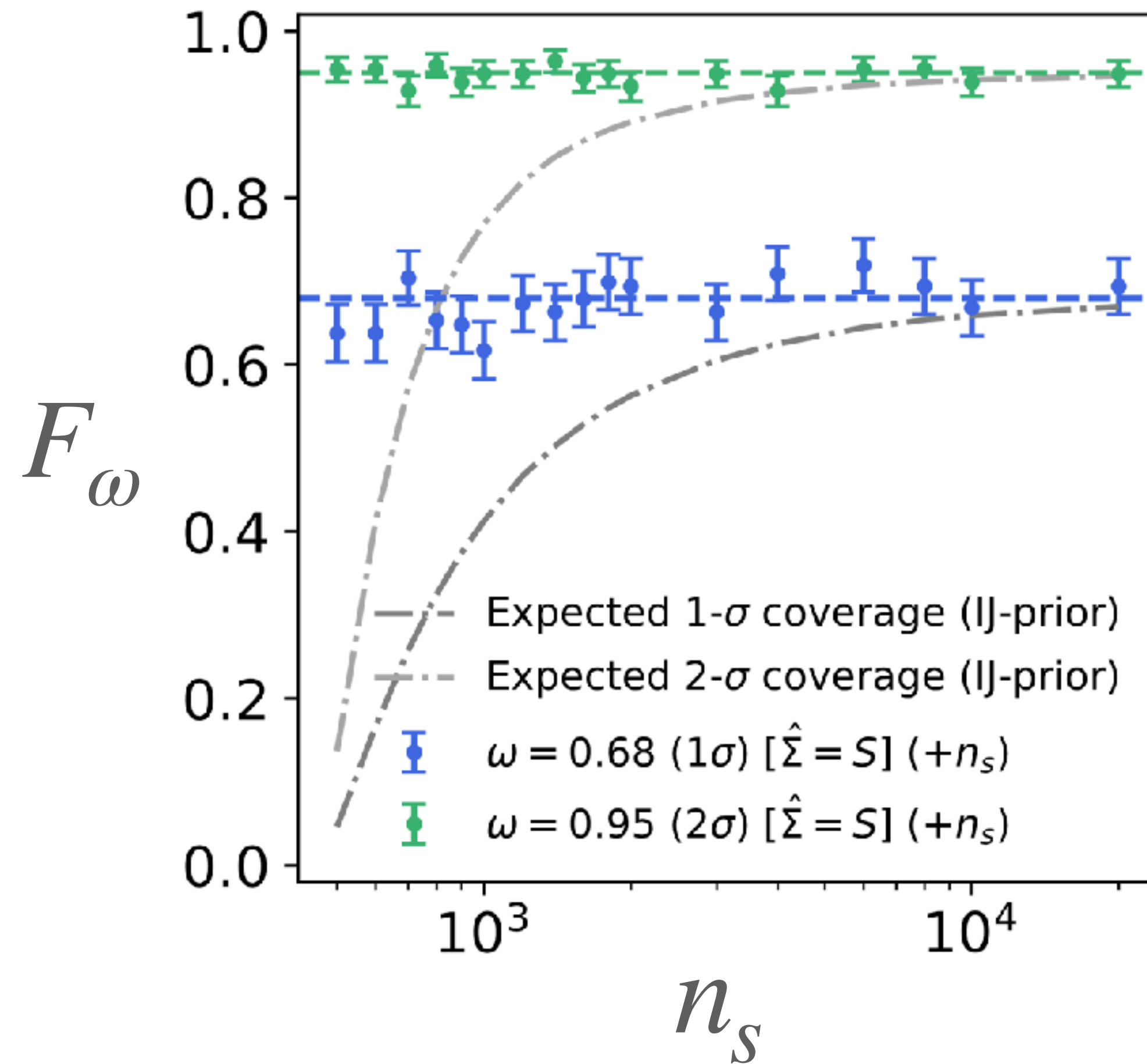
■ SBI $\hat{\theta}[x, \hat{\Sigma}]$

◆ SBI $\hat{\theta}[x, \text{diag}(\hat{\Sigma})]$

▲ SBI, $\hat{\theta}[x, \text{NN}]$

● SBI $\hat{\theta}[x, \Sigma]$

Posterior coverages: SBI



Good news

- Coverages are nominal, widths are inflated \implies **SBI *knows* about the Dodelson-Schneider effect and corrects for it!**
- **Low n_s with high $n_x \implies$ NN + NDE returns tighter constraints** (than $\mathcal{G} + \hat{\Sigma}$), where Σ is insurmountable (analytically or through simulations)
- **No assumptions on $p(x | \theta)$ and optimal compression \implies SBI fits true $p(x | \theta)$** with low n_s

Bad news

- **SBI returns diluted parameter constraints w.r.t. a Gaussian likelihood analysis for the same n_s** for Stage-III surveys
- **Compression is the crux:** we don't know how to compress data optimally, and multi-probe analyses increase n_x
 - **Moving noise around the analysis:** choose either $p(x | x[\theta], \hat{\Sigma})$, $p(\hat{\theta} | \theta, \hat{\Sigma}_{\hat{\theta}})$, $p(\hat{\theta} | \mu_{\text{NN}}, \hat{\Sigma}_{\text{NN}})$
 - **the neural density estimator likelihood fit cannot extract information that is lost here!**
- **Nuisances and complexity in $x[\theta]$, parameter dependence of Σ and non-Gaussian $p(x | \theta)$** will dilute information further, it is unclear how SBI responds to this...
- **Hyperparameter optimisation:** when n_x is large, training set is not as large as we'd like, meaning we overfit more to this during hyperparameter optimisation!

Two questions about SBI

- Does SBI produce "correct" posteriors in a set of repeated experiments, with no assumptions on the likelihood PDF?
 - How does this vary with n_s ?

Today

- Does SBI obtain more information than a Gaussian likelihood analysis for non-Gaussian statistics (e.g. the matter PDF) with a non-linear expectation $x[\theta]$?


Homert++26 (in prep.)

 **homerjed/sbiax**



 **homerjed.github.io**

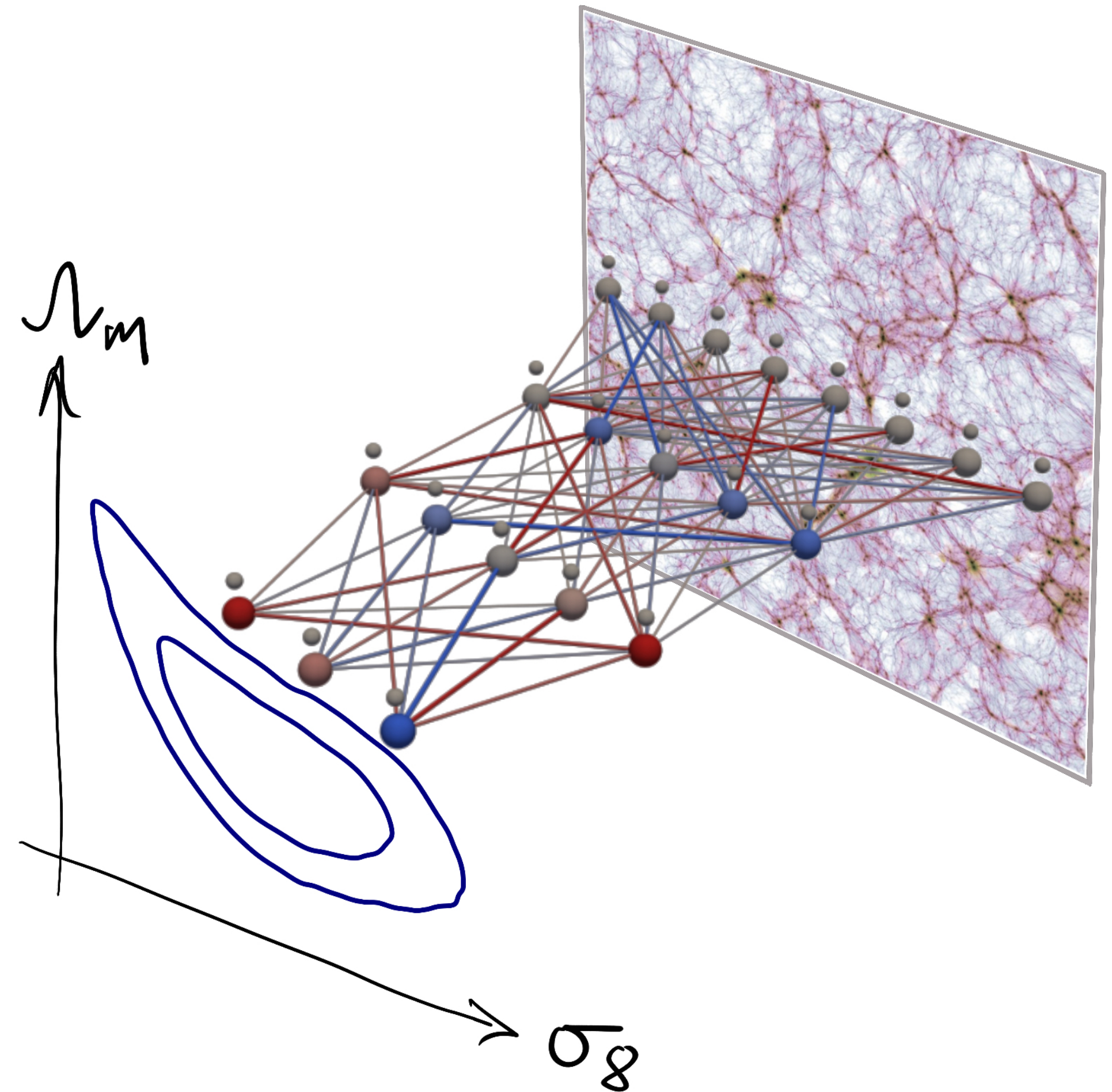
 **jed.homer@physik.lmu.de**

 **2412.02311**

 **LMU PHYSIK**

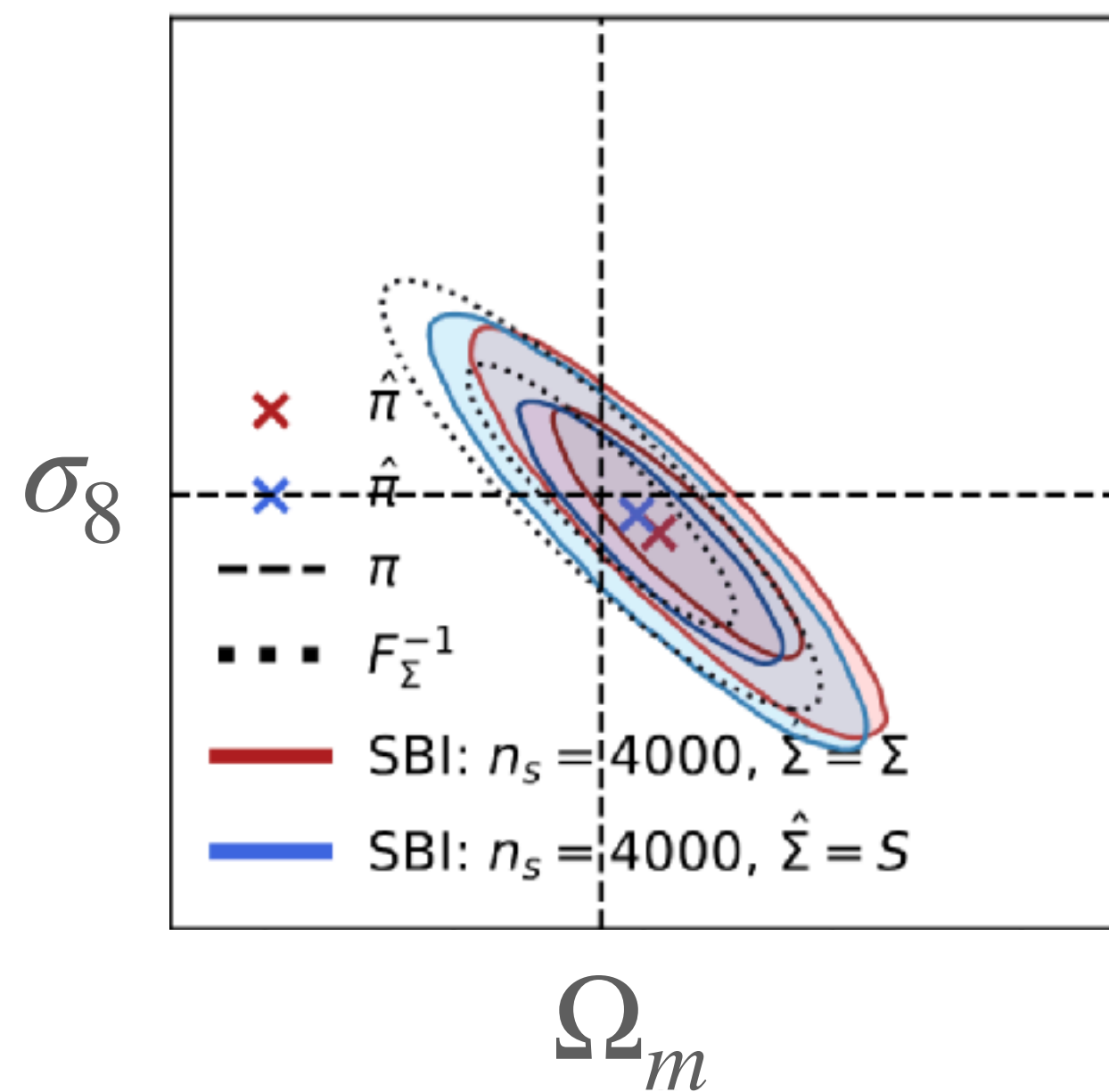
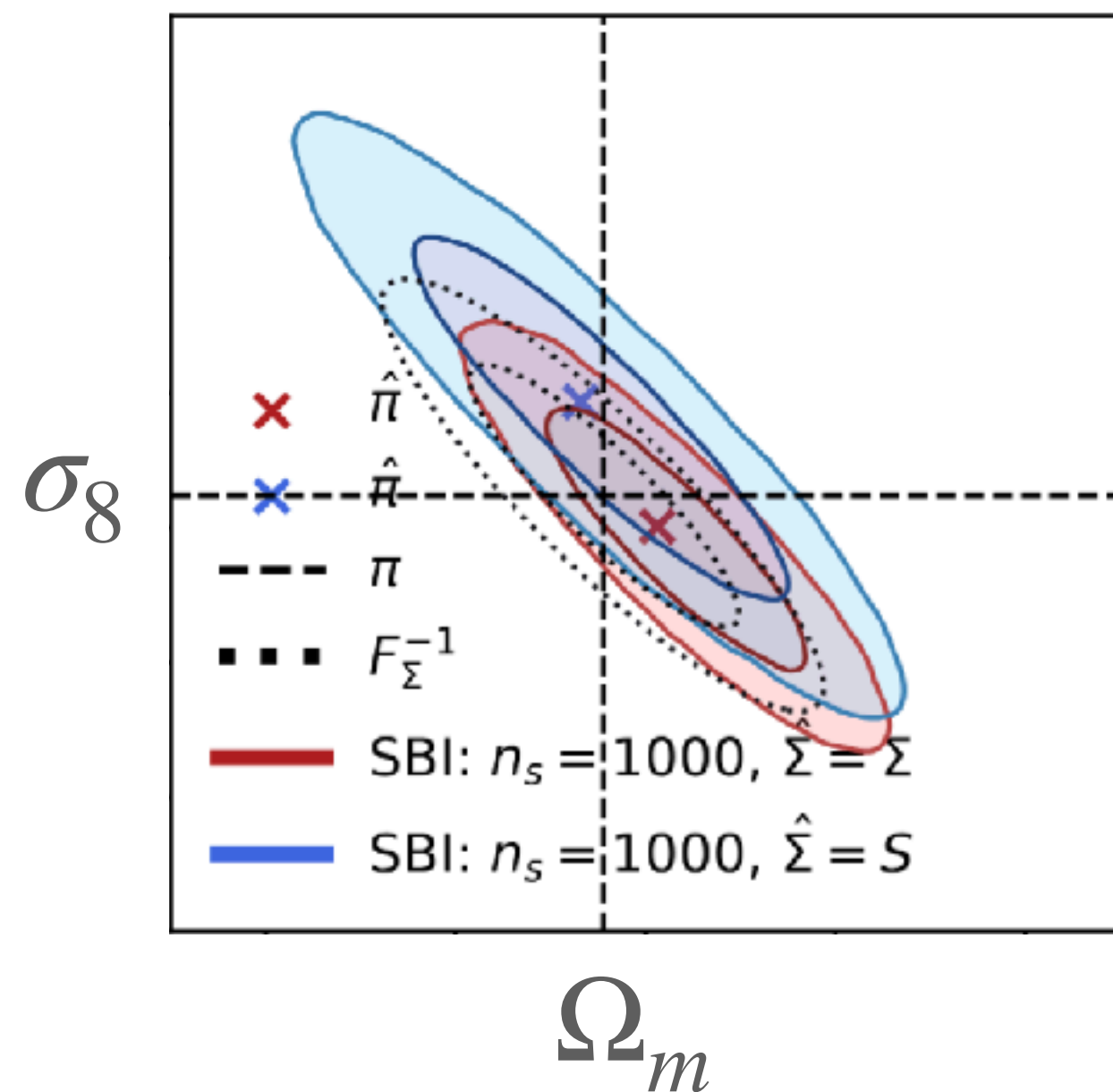



Munich Center for Machine Learning

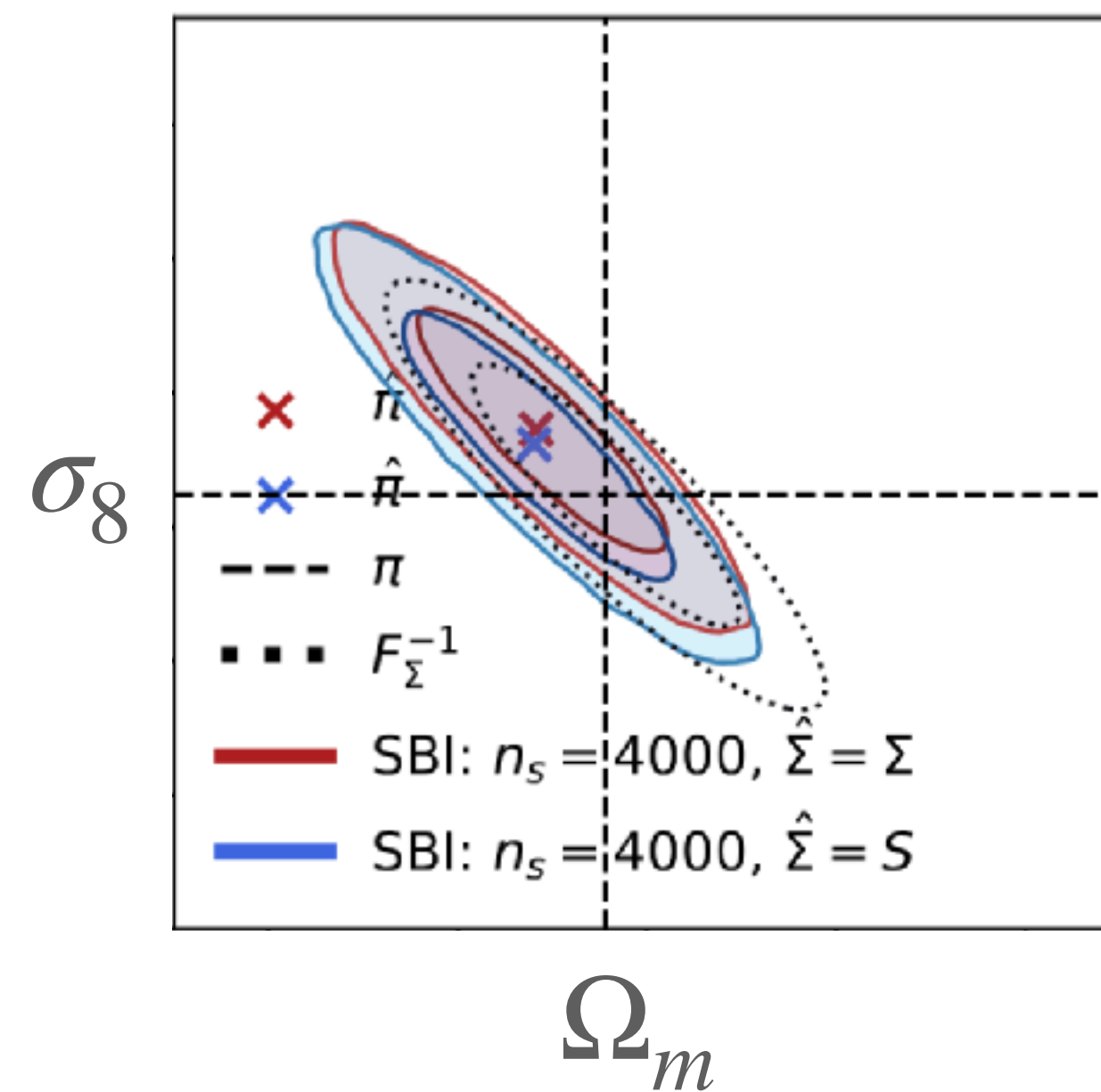
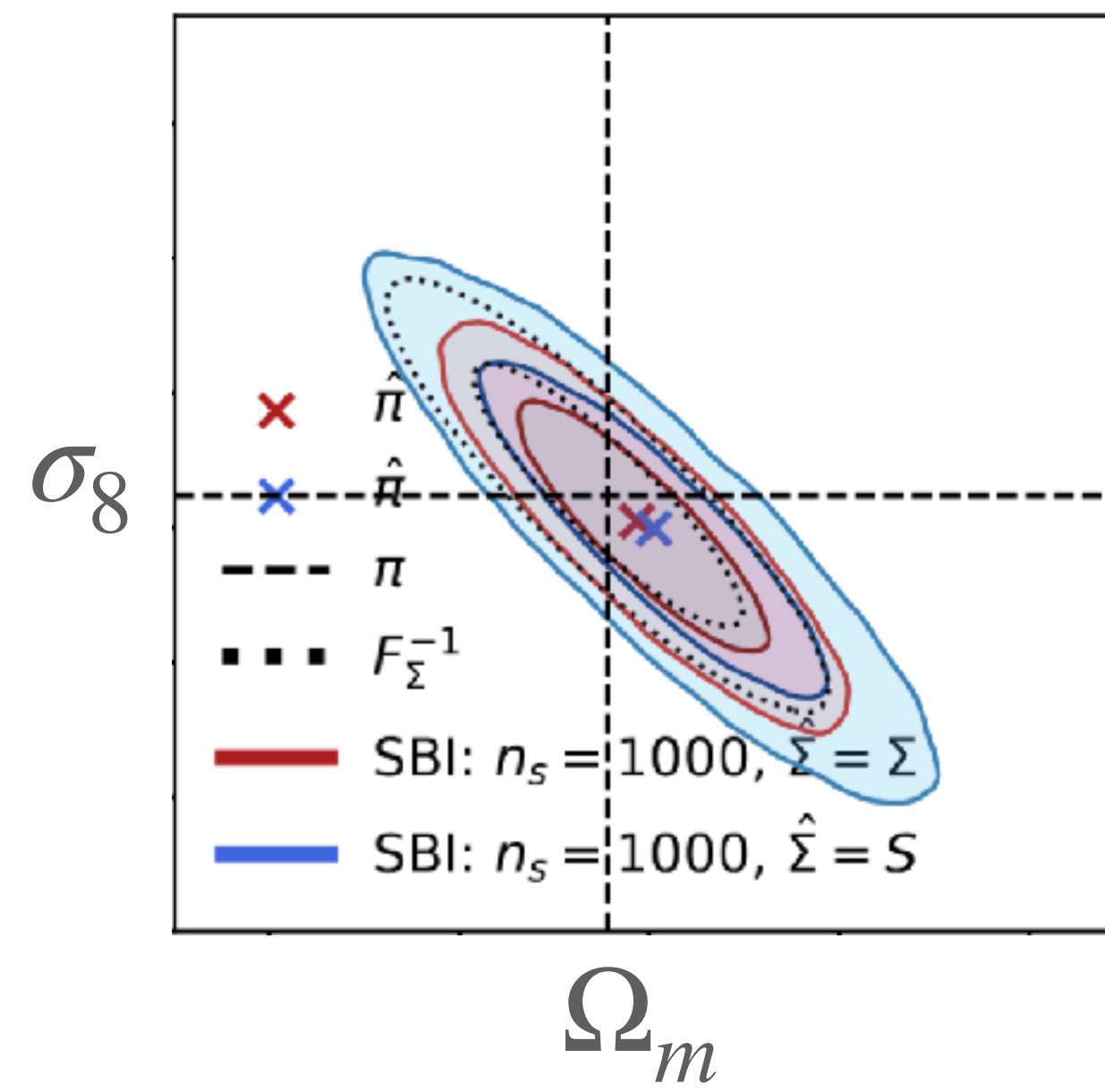


Reconstructed posteriors

MAFs



CNFs



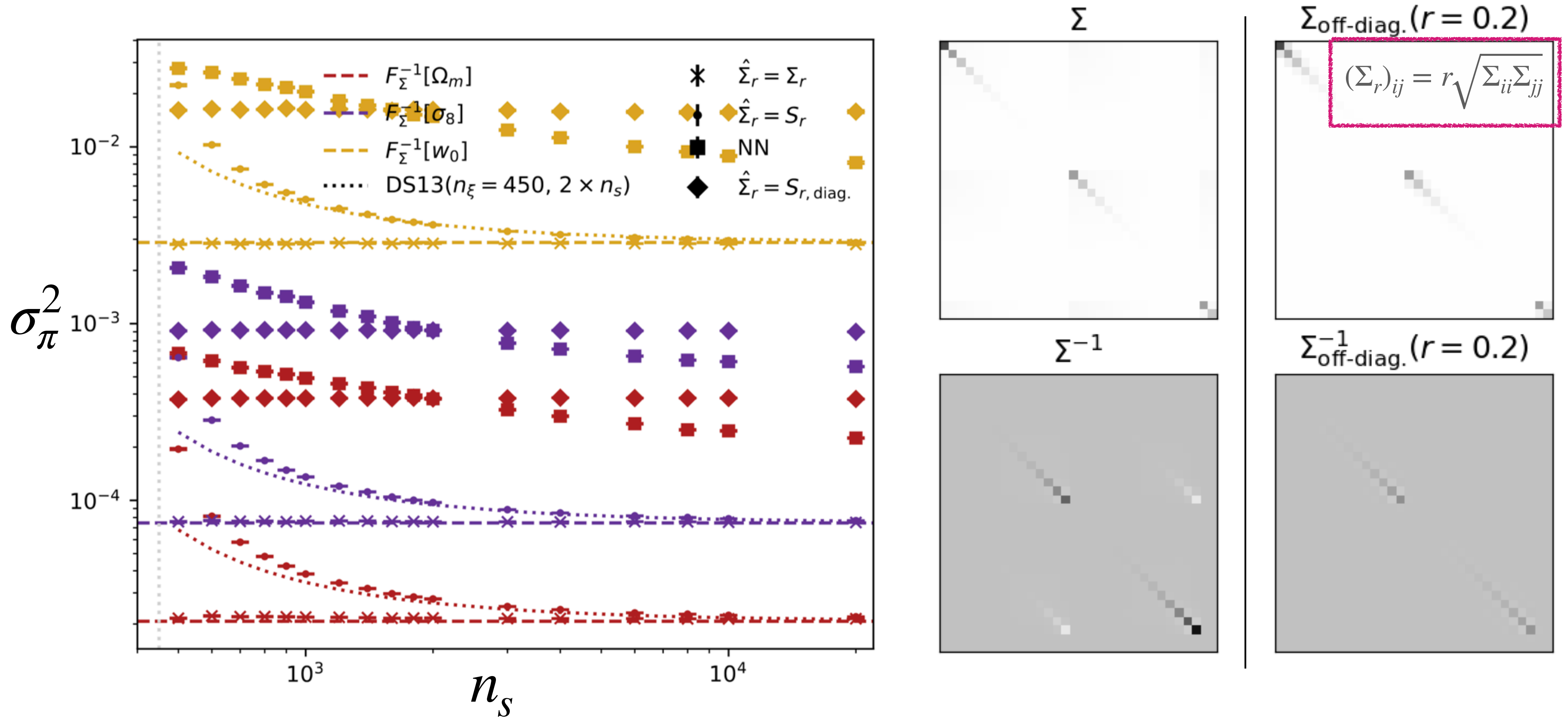
$$n_s = 1000$$

$$n_s = 1000 \times 2$$

$$n_s = 4000$$

$$n_s = 4000 \times 2$$

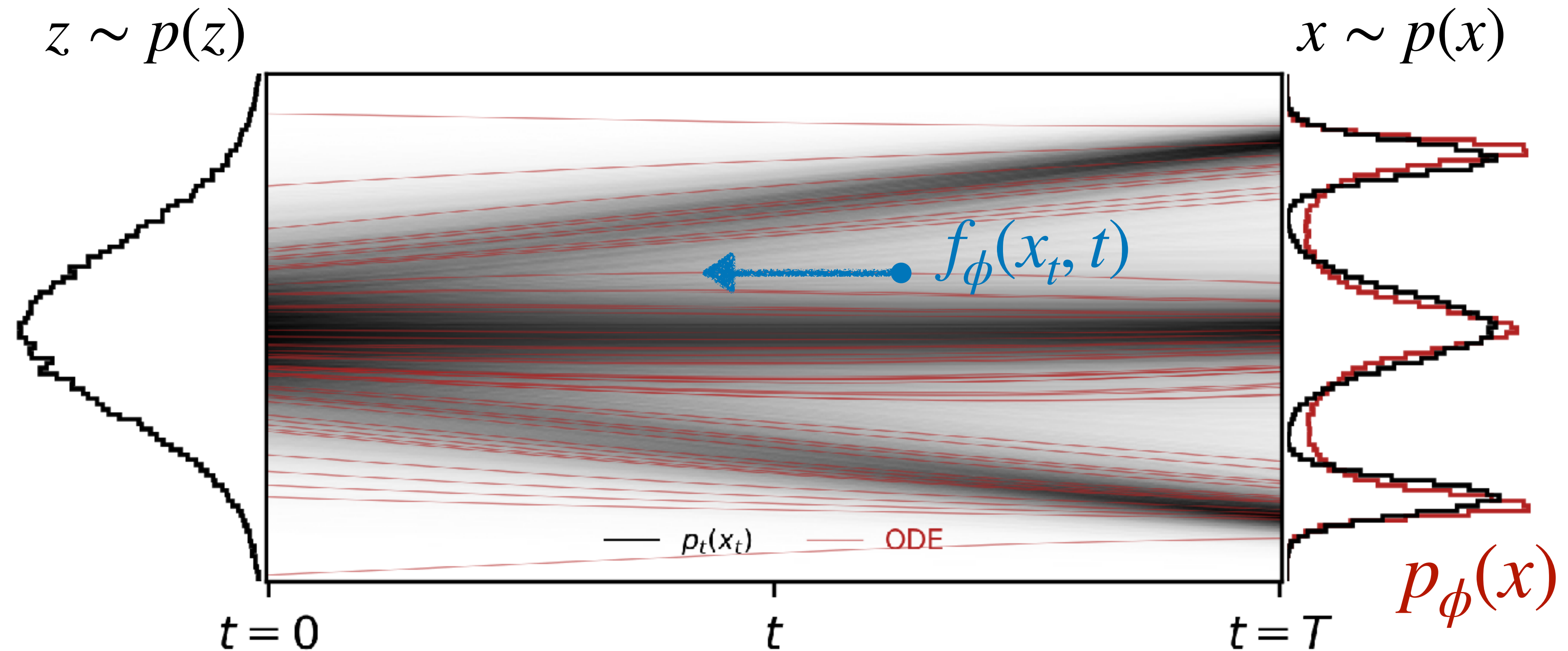
Where does NN compression fail?



- NN fails to summarise when data has a (strongly) non-diagonal covariance!

Hyperparameter optimisation

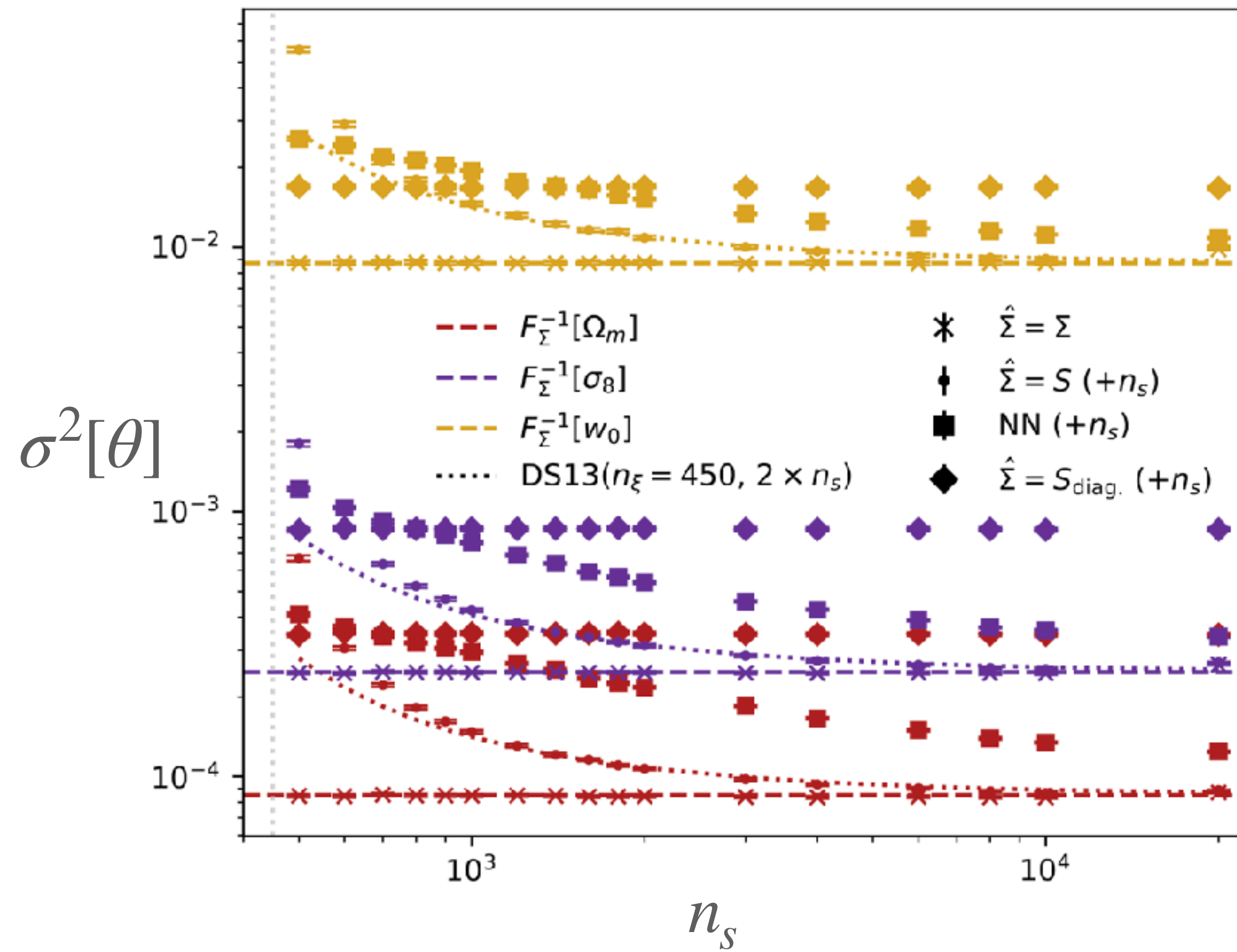
Continuous normalising flows



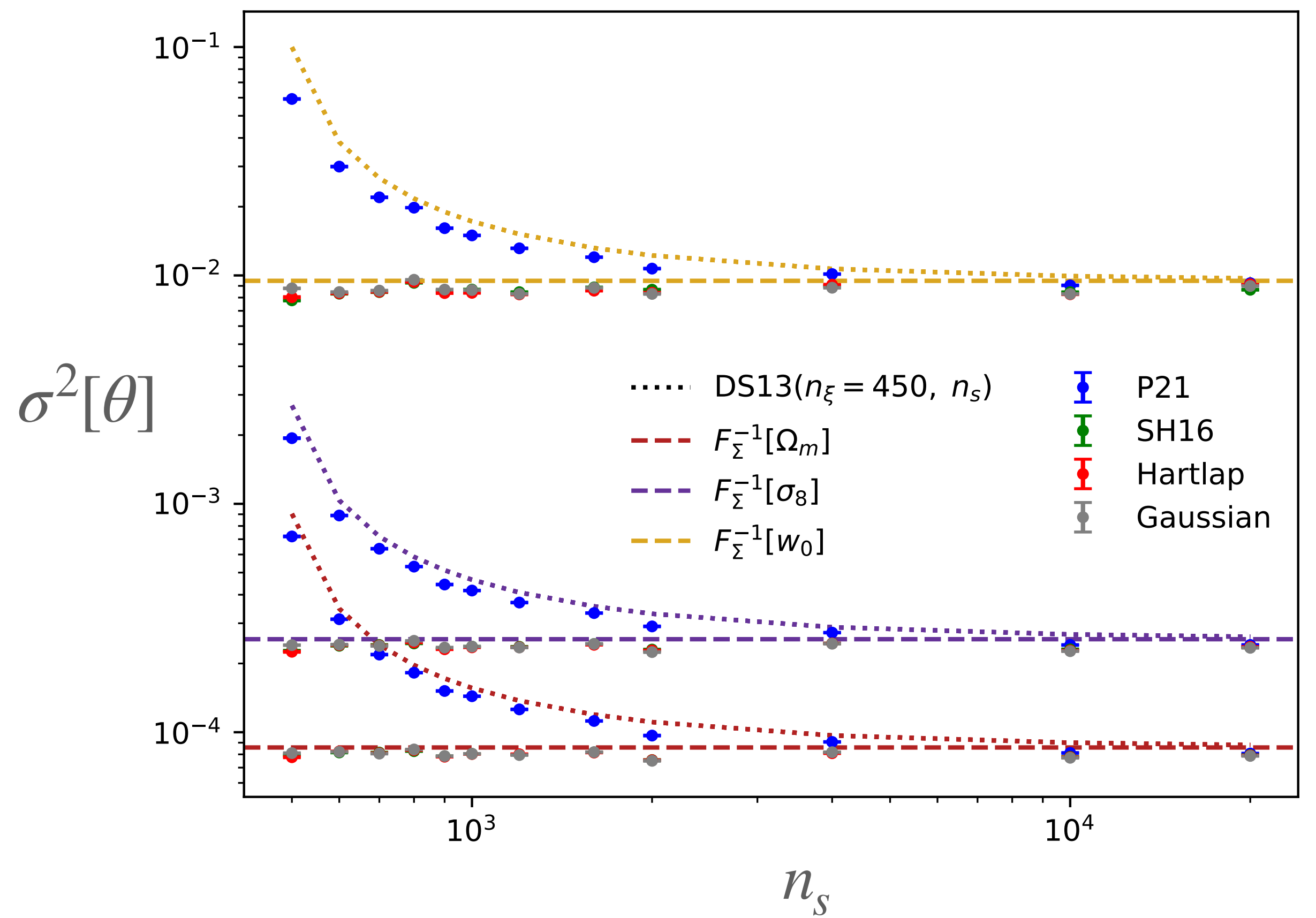
$$\log p_\phi(x) = \log p(z) + \int_{t=0}^{t=T} dt \nabla_{x_t} \cdot f_\phi(x_t, t)$$

SBI vs. Gaussian likelihood analysis

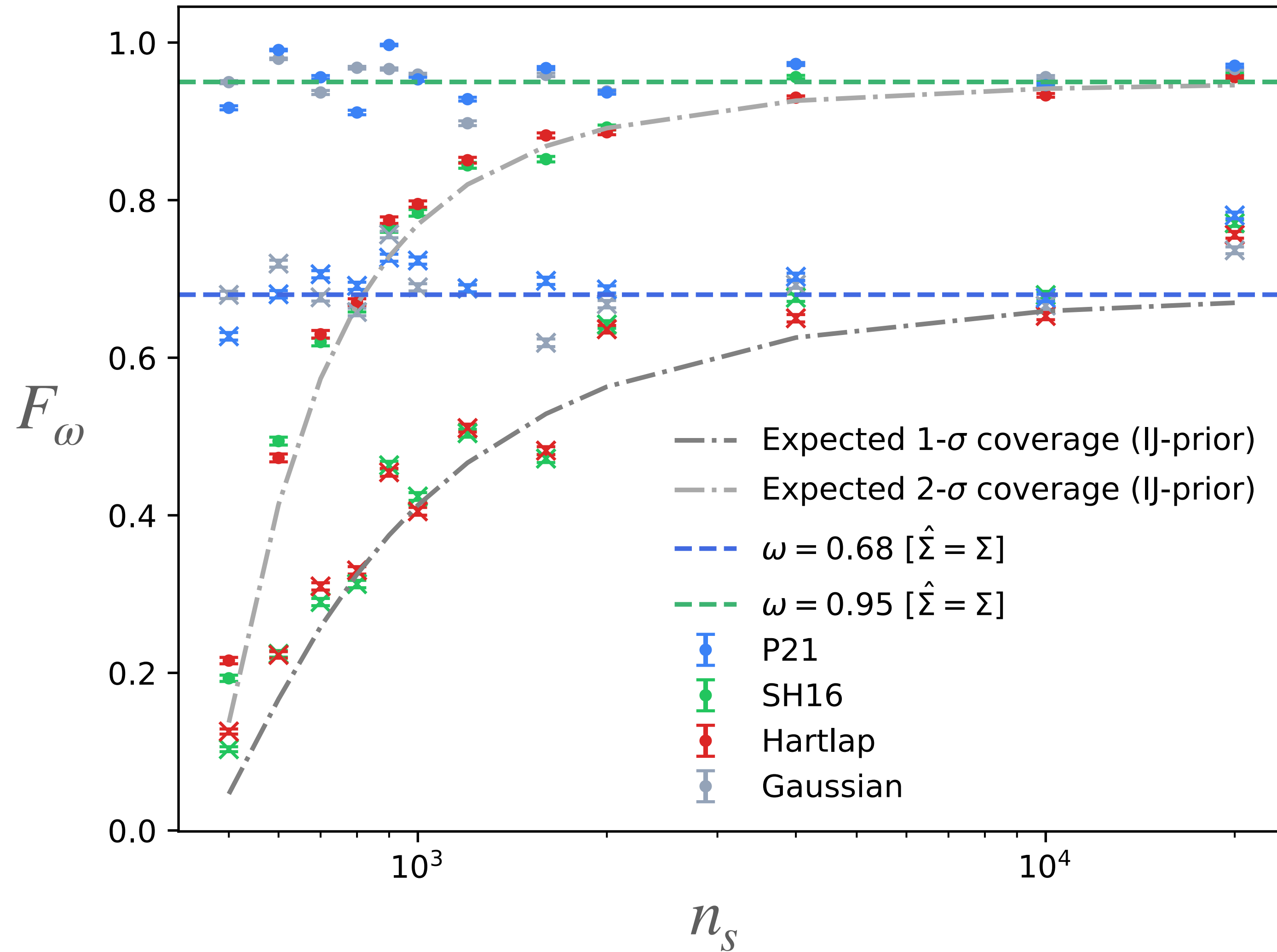
Posterior widths - SBI



Posterior widths - Gaussian likelihood analysis

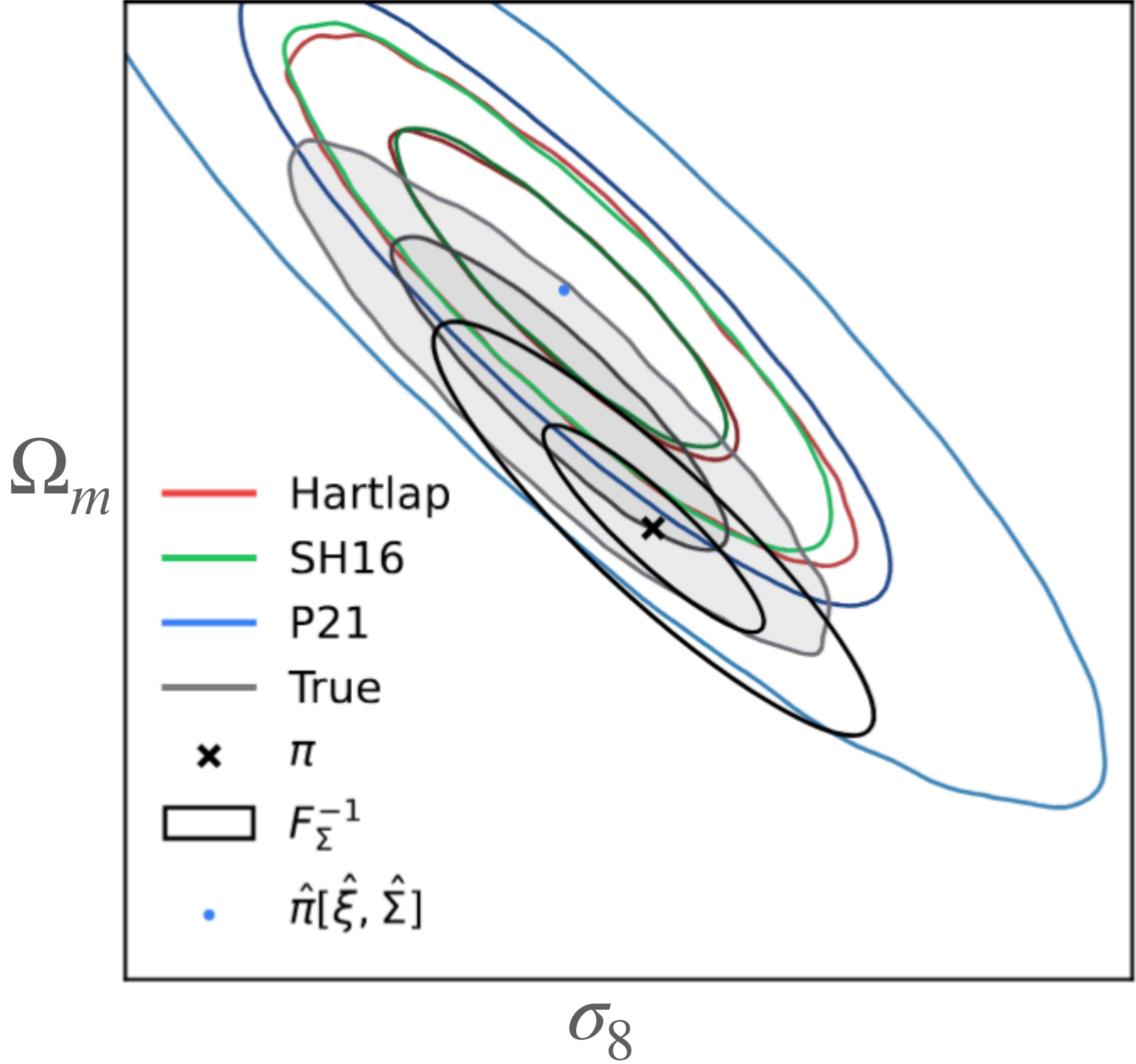


Posterior coverages - Gaussian likelihood analysis



The Percival++ posterior

Percival, Friedrich, Sellentin & Heavens 2021



$$p(\theta | \hat{x}, \hat{\Sigma}) = \int d\Sigma p(\theta, \Sigma | \hat{x}, \theta)$$

$$= \int d\Sigma p(\hat{x} | \theta, \Sigma) p(\hat{\Sigma} | \Sigma) p(\theta, \Sigma)$$

$$p(\theta, \Sigma) \propto |\Sigma|^{-\frac{m - n_S + n_X - 1}{2}}$$

$$\langle (\theta - \hat{\theta})(\theta - \hat{\theta})^T \rangle_{\theta | \hat{x}, \hat{\Sigma}, \hat{x}} = \langle (\hat{\theta} - \theta)(\hat{\theta} - \theta)^T \rangle_{\hat{\Sigma}, \hat{x}} \rightarrow m$$